

GIS Functions – Vector

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GIS Functions

- Data Retrieval
- Map Generalization
- Map Abstraction
- Map Sheet Manipulation
- Buffer Generation
- Polygon Overlay
- Geocoding
- Dynamic Segmentation
- Network Analysis

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Data Retrieval

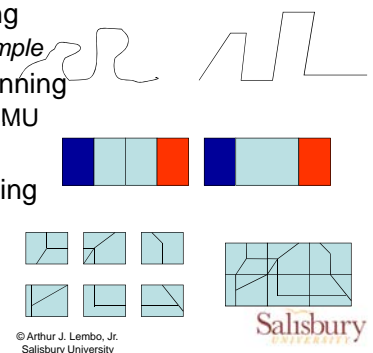
- Examples from ArcGIS
 - Browsing
 - Windowing
 - Zoom & pan
 - Multiple Map Query
 - identify
 - Attribute Query

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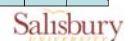


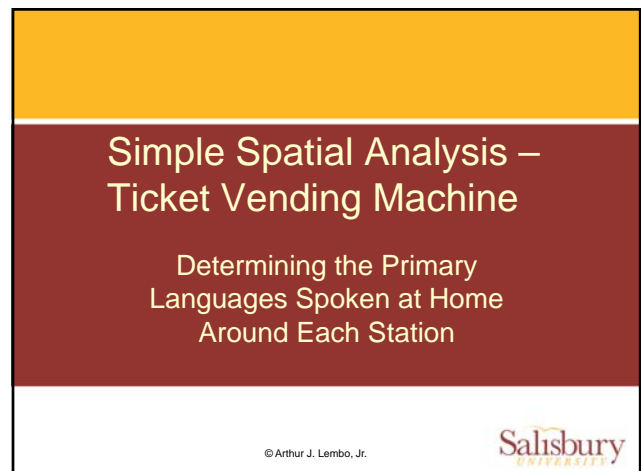
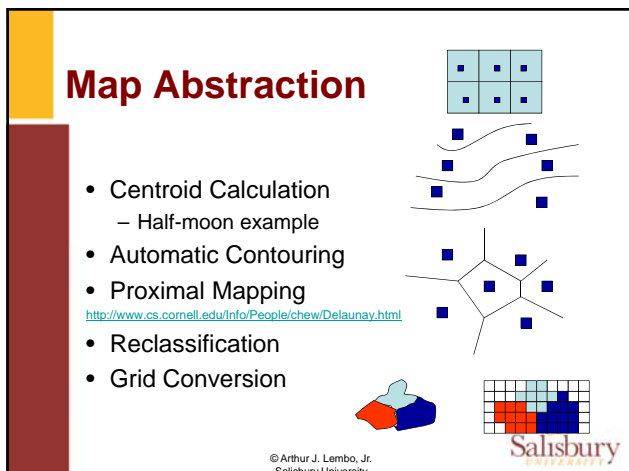
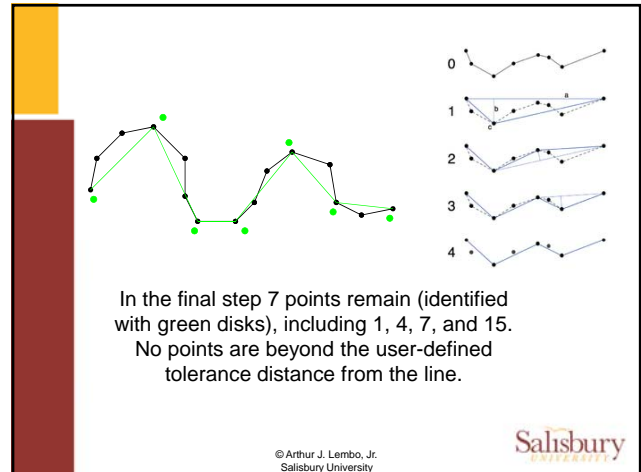
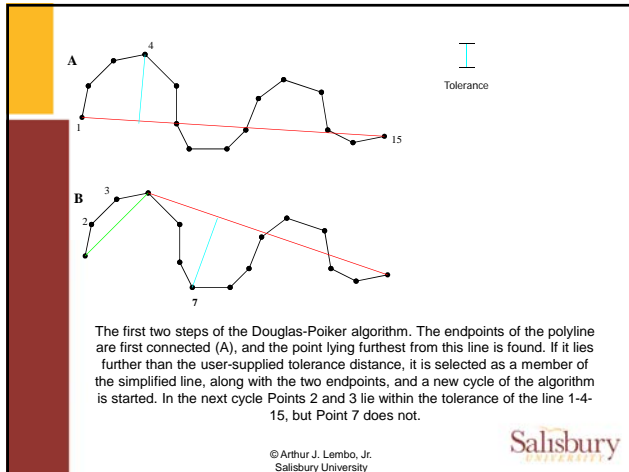
Map Generalization

- Line Thinning
 - *Hydro example*
- Polygon Thinning
 - Merging, MMU
- Dissolve
- Edge Matching
 - MAPJOIN

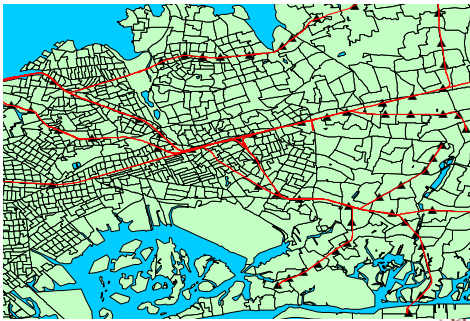


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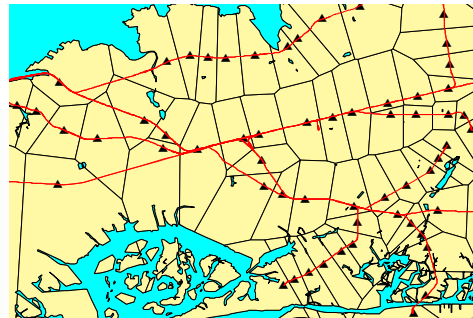


Base Data



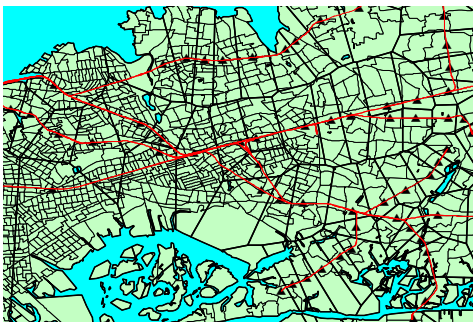
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Thiessen Polygons



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Overlay of Thiessen and Census Data



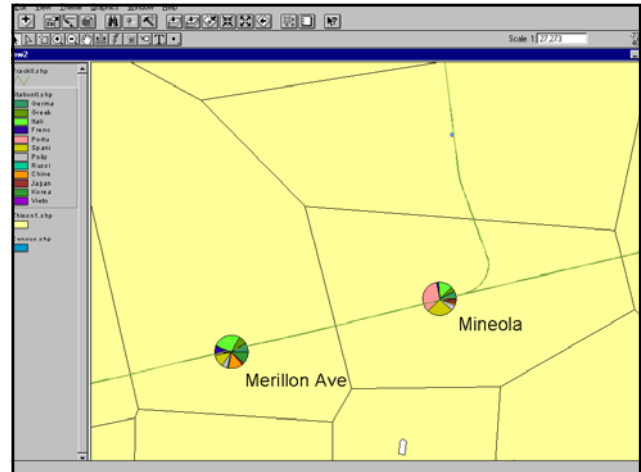
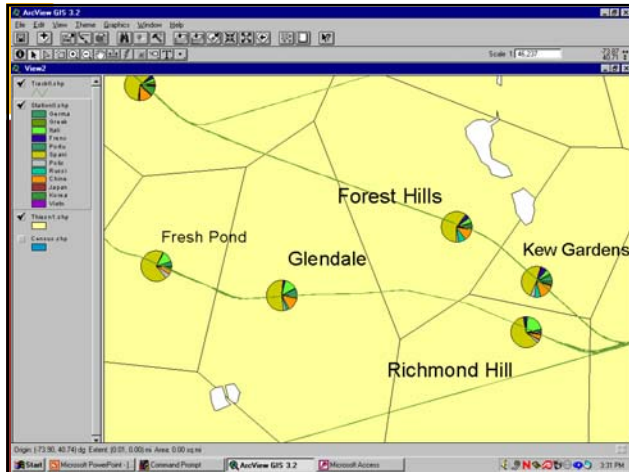
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SQL Query of Result

```
SELECT sum(CENSUS.LANG_GERMA) AS GERMA, sum(CENSUS.LANG_GREEK) AS GREEK,
sum(CENSUS.LANG_ITALI) AS ITALI, sum(CENSUS.LANG_FRENC) AS FRENC,
sum(CENSUS.LANG_PORTU) AS PORTU, sum(CENSUS.LANG_SPANI) AS SPANI,
sum(CENSUS.LANG_POLIS) AS POLIS, sum(CENSUS.LANG_RUSSI) AS RUSSI,
sum(CENSUS.LANG_CHINE) AS CHINE, sum(CENSUS.LANG_JAPAN) AS JAPAN,
sum(CENSUS.LANG_KOREA) AS KOREA, sum(CENSUS.LANG_VIETN) AS VIETN, CENSUS.STATION AS
```

STATION
FROM CENSUS
GROUP BY STATION;

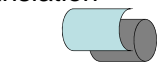
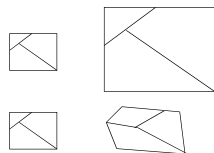
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2	123	45	67	89	101	112	134	156	178	199	210	221	2
3	123	45	67	89	101	112	134	156	178	199	210	221	3
4	123	45	67	89	101	112	134	156	178	199	210	221	4
5	123	45	67	89	101	112	134	156	178	199	210	221	5
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99	123	45	67	89	101	112	134	156	178	199	210	221	99
100	123	45	67	89	101	112	134	156	178	199	210	221	100



Map Sheet Manipulation

- Scale Change
- Rubbersheeting
- Projection Change
- Coordinate Rotation/Translation

mathcad example



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Matrices

- If you are going to understand transformation algorithms, you should understand something about matrix algebra
- **Matrix:** a set of numbers or symbols arranged in a square or rectangular array of "m" rows and "n" columns. The arrangement is such that certain defined mathematical operations can be performed in a systematic and efficient way

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Linear equations and matrices

- Given a set of linear equations

$$\begin{array}{rcl} a_1x_1 + a_1x_2 + a_1x_3 & = & c_1 \\ a_2x_1 + a_2x_2 + a_2x_3 & = & c_2 \\ a_3x_1 + a_3x_2 + a_3x_3 & = & c_3 \end{array} \quad \begin{array}{rcl} x + y - z & = & -8 \\ 2x - y + z & = & -4 \\ -x + 2y + 2z & = & 21 \end{array}$$

- We can define them in matrix form

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix}$$

- And further define them in matrix notation

$$AX = C$$

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- So, if we have a system of linear equations

$$AX = C$$

- We can algebraically reformat the equation by pre-multiplying both sides by the identity matrix

$$AX = C$$

$$(A^T A)^{-1} A^T AX = (A^T A)^{-1} A^T C$$

$$IX = (A^T A)^{-1} A^T C$$

$$X = (A^T A)^{-1} A^T C$$

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Solving simultaneous equations

- We can solve the following equation simultaneously through based algebraic manipulation

$$\begin{array}{rcl} x + 5y & = & -8 \\ -x - 2y & = & -1 \\ \hline \text{now add the two equations} & & \\ x + 5y - 8 & & \\ -x - 2y - 1 & & \\ \hline 3y & = & -9 \\ y & = & -3 \end{array}$$

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Solving simultaneous equations with matrices

- Or, we can use matrices

$$\begin{array}{rcl} x + 5y & = & -8 \\ -x - 2y & = & -1 \end{array}$$

$$\begin{bmatrix} 1 & 5 \\ -1 & -2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -8 \\ -1 \end{bmatrix}$$

$$\underset{A}{\quad} \underset{X}{\quad} = \underset{C}{\quad}$$

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More complicated formulas

$$\begin{aligned}x + 5y &= -8 \\ -x - 2y &= -1\end{aligned}$$

$$A = \begin{pmatrix} 1 & 5 \\ -1 & -2 \end{pmatrix} \quad C = \begin{pmatrix} -8 \\ -1 \end{pmatrix}$$

$$(A^T A)^{-1} A^T C = \begin{pmatrix} 7 \\ -3 \end{pmatrix}$$

$$\begin{aligned}x + y + z &= -8 \\ 3x - y + z &= -4 \\ -x + 2y + 2z &= 21\end{aligned}$$

$$A = \begin{pmatrix} 1 & 1 & 1 \\ 3 & -1 & 1 \\ -1 & 2 & 2 \end{pmatrix} \quad C = \begin{pmatrix} -8 \\ -4 \\ 21 \end{pmatrix}$$

$$(A^T A)^{-1} A^T C = \begin{pmatrix} -3 \\ 2 \\ 7 \end{pmatrix}$$

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Transformation Methods

- Methods based on polynomials
 - Linear Conformal
 - Affine
 - Second Order Polynomial
- Methods based on finite element analysis
 - Piecewise Linear Homeomorphism



a) Original Map b) 3 Control Points c) 9 Control Points
Improvements in rubbersheeting with the addition of more control points

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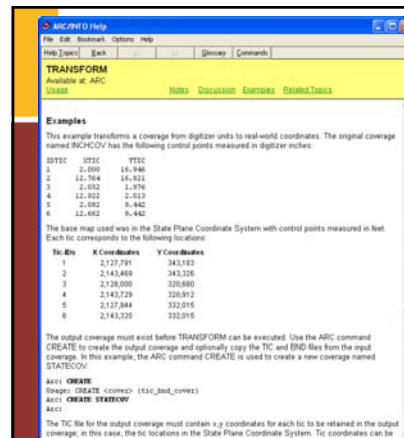
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Transformation Methods (cont.)

- Methods based on adjustment computations
 - Adjustment of Indirect Observations
 - Adjustment of Indirect Observations and Geometric Constraints

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TRANSFORM
Available at: ARC
Syntax: TRANSFORM *input,output* *type* *parameters*

Example:
TRANSFORM INCHOUT STATOV SIZEABILITY
Transforming coordinates for coverage inchout
Scale (X,Y) = (1403.794,1403.794)
Rotation (degrees) = (0.377) Translation = (2124800.900,317942.729)
RM Error (input,output) = (0.562,240.508)

Transformation Parameters:
Scale (X,Y) = (1403.794,1403.794)
Rotation (degrees) = (0.377) Translation = (2124800.900,317942.729)
RM Error (input,output) = (0.562,240.508)

Transformation Formula:
$$X = a_0 + a_1 X' + a_2 Y'$$

$$Y = b_0 + b_1 X' + b_2 Y'$$

Transformation Parameters:
a0 = 1403.794 a1 = 0.000 a2 = 0.000
b0 = 317942.729 b1 = 0.000 b2 = 0.000

Transformation Results:

ID	Input X	Input Y	Output X	Output Y	RM Error
1	2.000	16.946	1405.794	1405.794	0.000
2	2127791.000	343183.000	2129914.694	343400.000	-0.000
3	2143469.000	343183.000	2145592.694	343400.000	-0.000
4	2143469.000	343183.000	2145592.694	343400.000	-0.000
5	2143469.000	343183.000	2145592.694	343400.000	-0.000
6	2143469.000	343183.000	2145592.694	343400.000	-0.000

Affine Transformation

- 6 transformation parameters
 - 2 scale changes, one rotation, two translations of the origin, one perpendicularity
 - $a_x + b_y + c = X + \text{some residual } (v_x)$
 - $d_x + e_y + f = Y + \text{some residual } (v_y)$
- Additional scale parameter
- Good for accounting for film deformation

TRANSFORM
Available at: ARC
Syntax: TRANSFORM *input,output* *type* *parameters*

Example:
TRANSFORM INCHOUT STATOV SIZEABILITY
Transforming coordinates for coverage inchout
Scale (X,Y) = (1403.794,1403.794)
Rotation (degrees) = (0.377) Translation = (2124800.900,317942.729)
RM Error (input,output) = (0.562,240.508)

Transformation Parameters:
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RM Error (input,output) = (0.562,240.508)

Transformation Formula:
$$X = a_0 + a_1 X' + a_2 Y'$$

$$Y = b_0 + b_1 X' + b_2 Y'$$

Transformation Parameters:
a0 = 1403.794 a1 = 0.000 a2 = 0.000
b0 = 317942.729 b1 = 0.000 b2 = 0.000

Transformation Results:

ID	Input X	Input Y	Output X	Output Y	RM Error
1	2.000	16.946	1405.794	1405.794	0.000
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3	2143469.000	343183.000	2145592.694	343400.000	-0.000
4	2143469.000	343183.000	2145592.694	343400.000	-0.000
5	2143469.000	343183.000	2145592.694	343400.000	-0.000
6	2143469.000	343183.000	2145592.694	343400.000	-0.000

Second Order Polynomial

- 12 transformation parameters
- $$a + b_x + c_y + d_x^2 + e_{xy} + f_y^2$$

$$g + h_x + i_y + j_x^2 + k_{xy} + l_y^2$$
- Frequently used as an approximation for more complicated functions
- Polynomials have a tendency to over-model a function

TRANSFORM
Available at: ARC
Syntax: TRANSFORM *input,output* *type* *parameters*

Example:
TRANSFORM INCHOUT STATOV SIZEABILITY
Transforming coordinates for coverage inchout
Scale (X,Y) = (1403.794,1403.794)
Rotation (degrees) = (0.377) Translation = (2124800.900,317942.729)
RM Error (input,output) = (0.562,240.508)

Transformation Parameters:
Scale (X,Y) = (1403.794,1403.794)
Rotation (degrees) = (0.377) Translation = (2124800.900,317942.729)
RM Error (input,output) = (0.562,240.508)

Transformation Formula:
$$X = a_0 + a_1 X' + a_2 Y'$$

$$Y = b_0 + b_1 X' + b_2 Y'$$

Transformation Parameters:
a0 = 1403.794 a1 = 0.000 a2 = 0.000
b0 = 317942.729 b1 = 0.000 b2 = 0.000

Transformation Results:

ID	Input X	Input Y	Output X	Output Y	RM Error
1	2.000	16.946	1405.794	1405.794	0.000
2	2127791.000	343183.000	2129914.694	343400.000	-0.000
3	2143469.000	343183.000	2145592.694	343400.000	-0.000
4	2143469.000	343183.000	2145592.694	343400.000	-0.000
5	2143469.000	343183.000	2145592.694	343400.000	-0.000
6	2143469.000	343183.000	2145592.694	343400.000	-0.000

Polynomial Example

2ND ORDER POLYNOMIAL

5TH ORDER POLYNOMIAL

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Problems with Traditional Methods

- Limited transformation parameters
- Coordinate exchange without true error removal
- Residual error distribution only among control points used

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Finite Element Analysis (Piecewise Linear Homeomorphism)

- Breaks transformation into multiple pieces (triangles)
- Determines transformation parameters for each triangle
- Transforms lines within each triangle using affine transformation

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Adjustment Using Indirect Observations

- Determines corrections for lines that produce the highest probability of a simultaneous occurrence
- Errors distributed among all lines
- Adjustment occurs with consideration for the relationship among all lines

$${}_m A_{nn} X_1 = {}_m L_1 + {}_m V_1$$

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Adjustment Using Indirect Observations and Geometric Constraints

- Determines corrections for lines that produce the highest probability of a simultaneous occurrence, AND, satisfies specific geometric constraints.
- Solves for two sets of equations

$${}_m A_{nn} X_1 = {}_m L_1 + {}_m V_1$$

$${}_s C_{nn} X_1 = {}_m g_1$$

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Transforming Data

Getting a handle on the WTC
Damage when no data was
available

www.nyu.edu/icis/research/wtc

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Evaluating Water Distribution System Damage

- Data Sources
 - Digital orthophotography – not clear but registered with a geographic coordinate system
 - Aerial photographs – clear, but unregistered
 - DEP water main map – clear, but unregistered
- Issues
 - Maps/photos were not in the correct geographic position, so viewing them simultaneously was impossible
- Solution
 - Register all data to a common basemap and coordinate system within a GIS

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DEP Data



DEP map showing damaged
mains after September 11.
Obtained from NYC DEP



DEP map showing mains,
with size. Obtained from
NYC DEP

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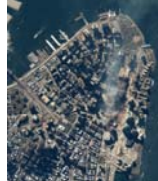
Aerial Photography



High resolution aerial photograph taken by NOAA, downloaded from the Internet



Aerial photograph downloaded from the Internet - Pre September 11th



Aerial photograph taken on September 15. Downloaded from the Internet

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Digital Orthophotography



Digital orthophotograph of Manhattan. Downloaded from NYS Digital Ortho Quarter Quad archive



Same photograph from left, zoomed in. Shadows from buildings make seeing the streets more difficult

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Registration Process Using ArcInfo

- Obtain digital orthophotograph that is already registered in UTM coordinate system
- Identify common points between higher resolution photographs and digital orthophotograph
- Register photographs to orthophoto coordinate system
- Register DEP map with newly positioned aerial photographs

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Results of Registration

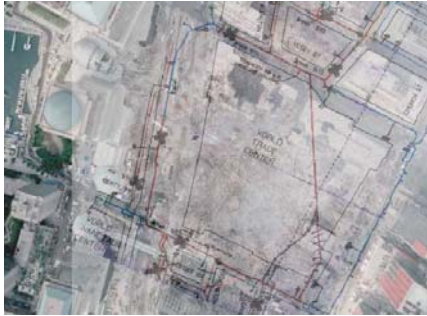


Digital Ortho
Pre Sept 11
Sept 15
High Res
DEP Map

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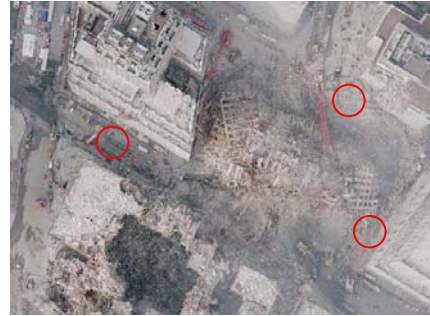
Damaged Mains



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Damaged Mains – Zoomed In



Note: due to the registration process, the absolute position of the main breaks may not be accurate

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Damaged Mains – Zoomed In



Note: due to the registration process, the absolute position of the main breaks may not be accurate

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Conclusion

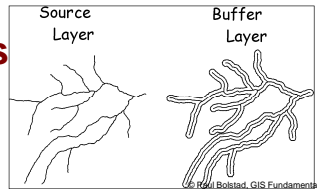
- Data was not readily available from many organizations.
- The use of registration functions within a GIS enabled disparate data sources to be assembled together into a common basemap
- Further analysis of the relationship between main breaks and debris piles could be explored

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Buffer Analysis

- A type of proximity analysis where a buffer zone is created to perform a search
- Search: specify a distance from a point (radius), line (corridor), area (area)
- Buffer: A zone around a point, line or area
 - Can also create concentric buffers around a point based on distances *example from wells & parcels*



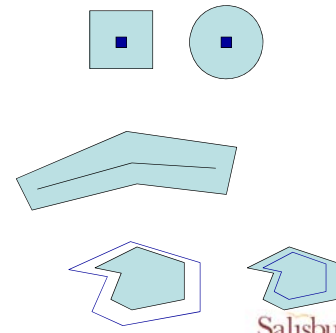
Review Mathcad equations
Review coordinate transform.
Review Conformal
Line generalization animation
Buffer
<http://www.sl.unimelb.edu.au/gisweb/menu.html>

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Buffer Generation

- Point
 - Circle
 - Square
- Line
 - Line Buffer
- Polygon
 - Interior
 - Exterior



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Overlay

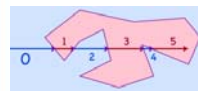
- Overlay is an operation in which sets of irregular, non-overlapping regions are merged to form a new set of geographic regions that the two initial sets share
- Relies on boolean operations

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Types of Overlay

- Polygon on Polygon
 - overlapping two or more polygons to create a new region
- Point in Polygon
 - determine which point features of specified characteristics fall in specified areas
 - Use ray tracing algorithm
- Line in Polygon
 - determine which line features of specified characteristics fall in specified areas



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Input layer 1	Input layer 2	Output layer
point 1, 2, 3	line A, B, C	point 1, 2, 3
point 1, 2, 3	polygon A, B, C	point 1, 2, 3
line 10, 11, 12	line A, B, C	line 10, 11, 12
line 10, 11, 12	polygon A, B, C	line 10, 11, 12
polygon 100, 101, 102	polygon A, B, C	polygon 100, 101, 102

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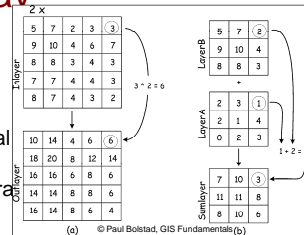
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Types of Overlay

- Raster Overlay

- in raster models this is known as map algebra
- in map algebra, the retrieval operations are boolean, multiply, recode and algebra
- overlay operations work on grid cells in a 1:1 relationship

2 2 2 3 3 3 2 2 2
2 2 2 2 2 3 3 3
2 2 2 1 1 1 3 3 3



B NOT A

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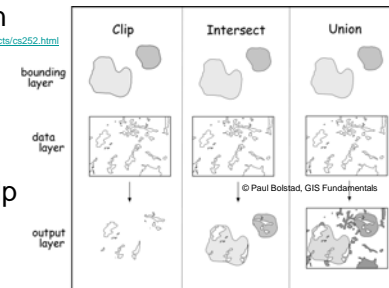
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Polygon Overlay

- Intersection

<http://www.lembo.brown.edu/~wg/projects/cs252.html>

- Clip
- Identity
- Union
- ArcGIS Help

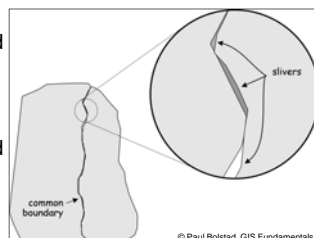


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Result of Overlay

- Sliver polygons formed by overlaying two features that are not exactly coincident
- “Fuzzy” tolerance used to remove sliver polygons
- Use ELIMINATE to remove sliver polygons



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Other GIS Overlay Operations

- ArcTools examples
- ARC/INFO Overlay Command Reference
- **CLIP** extracts features from a coverage that overlaps another coverage using the clip coverage as a 'cookie cutter'.
- **IDENTITY** computes the geometric intersection of two coverages. Only those features overlapping the feature extent of the first specified coverage are preserved. Feature attributes from both coverages are joined in the output coverage.
- **INTERSECT** computes the geometric intersection of two coverages. Only those features in the area common to both are preserved. Feature attributes from both coverages are joined in the output coverage.
- **RESELECT** extracts map features from a coverage based on their attribute values.
- **SPLIT** breaks a single coverage into many coverages.
- **UNION** computes the geometric intersection of two polygon coverages. All features and attributes of both coverages are preserved.

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Example of Basic Vector GIS Functions in Manifold GIS

- Dissolve
- Polygon Overlay
 - clip, merge, intersect, union
- Data Retrieval
- Point in Polygon
- Overlap (touching, intersection, etc.)

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Computational Geometry (the backbone of GIS operations)

- The use of mathematics to define spatial relationships between points, lines, and polygons
 - Distance
 - Line intersection
 - Distance between point and line
 - Polygon area
 - Determining clockwise rotation
 - Point in Polygon (see line intersection)
 - Thiessen Polygon example

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	Line Smoothing	Area calculation	Buffering	Topological Overlay	Point in polygon	Topology creation
Line Distance	X		X			
Area / Perimeter		X		x		X
Distance from point to a line			X			X
Intersection			X	X	X	X

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