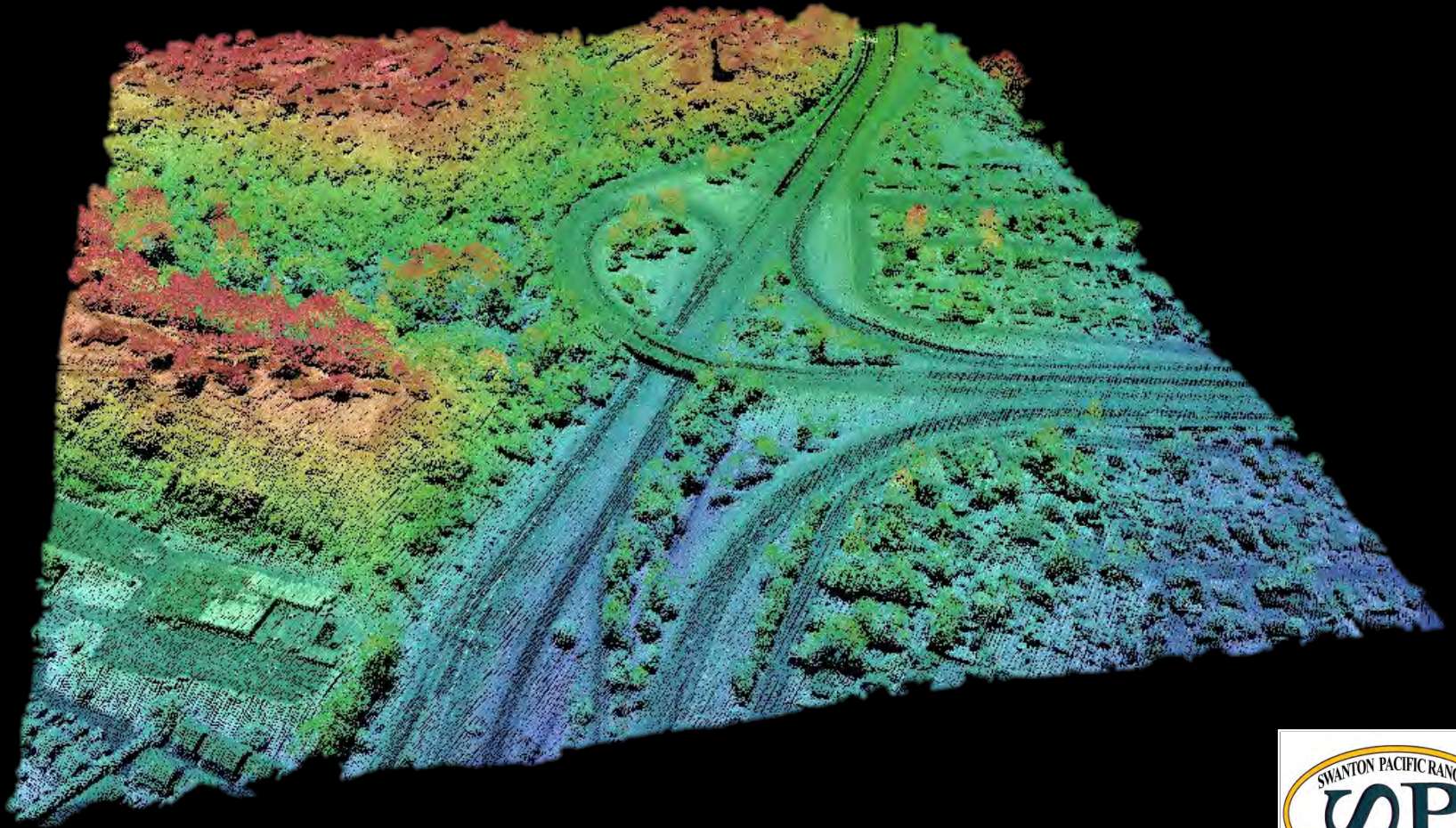


LiDAR Tools and Workflows

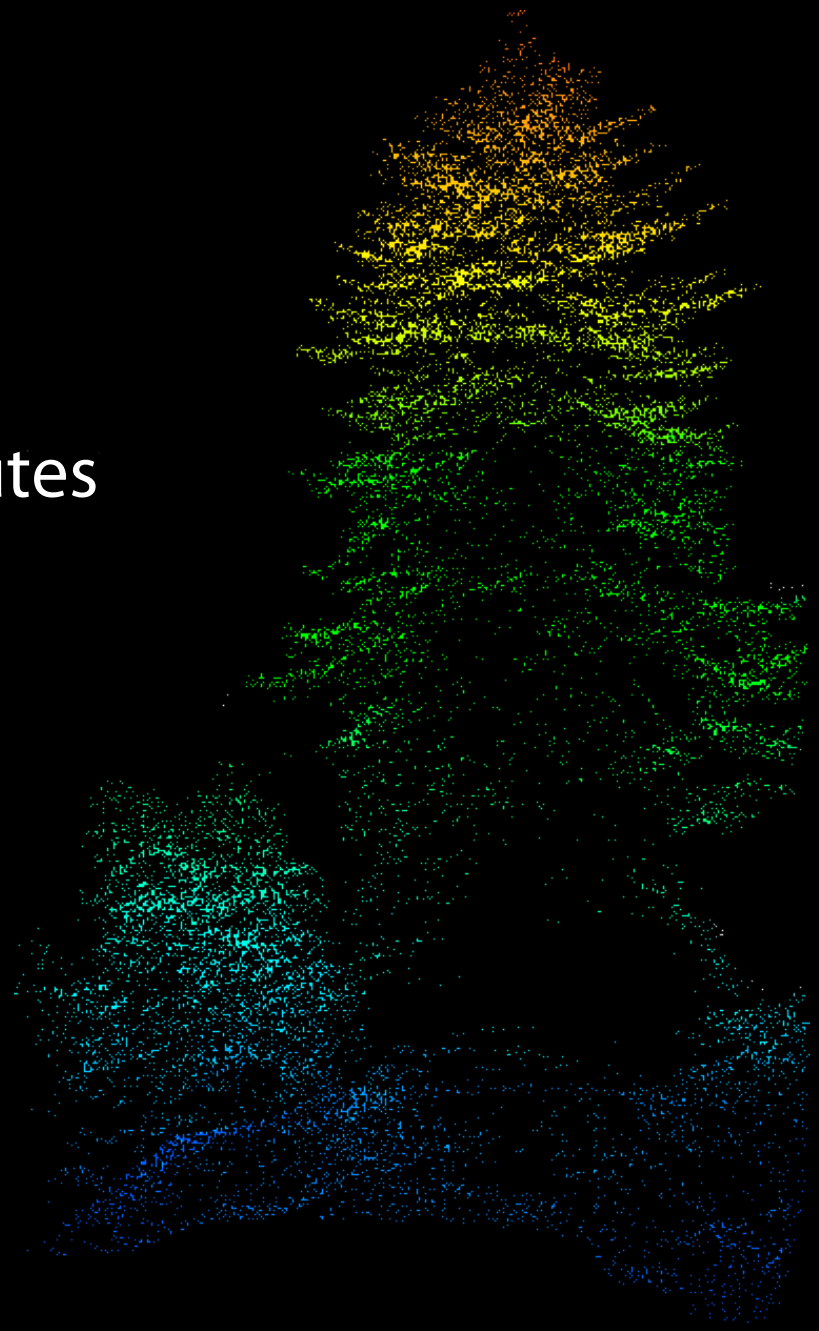


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Natural Resources Management Department



Overview

- LiDAR Data Collection
- LAS Data Format and Attributes
- Data Sources and Products
- Tools and Workflows



Light Detection and Ranging

Survey Aircraft

- Laser Rangefinder
- Differential GPS
- Inertial Measurement Unit



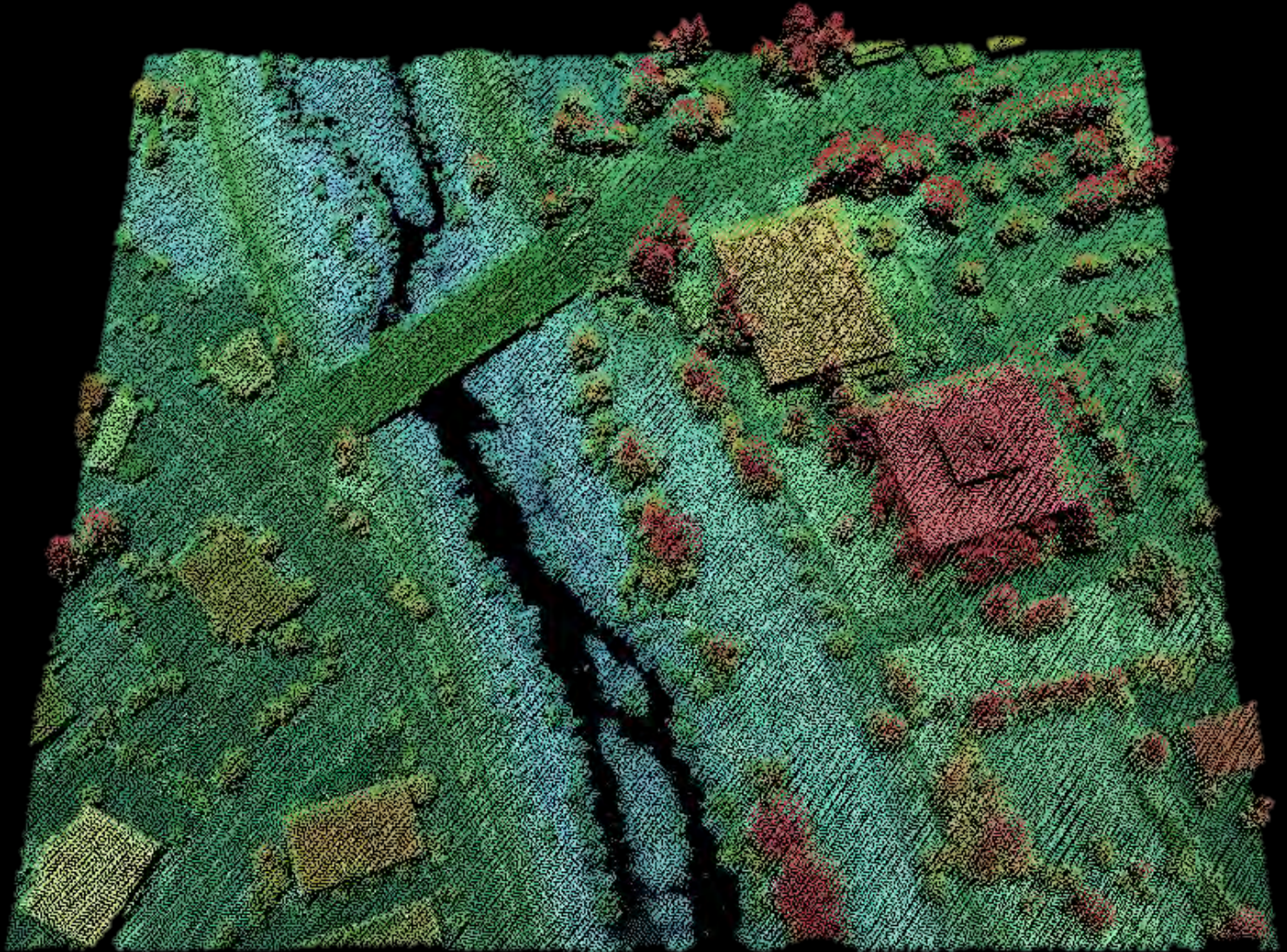
~3,000 ft.

elapsed time:
3 microseconds



Ground Control (GPS)

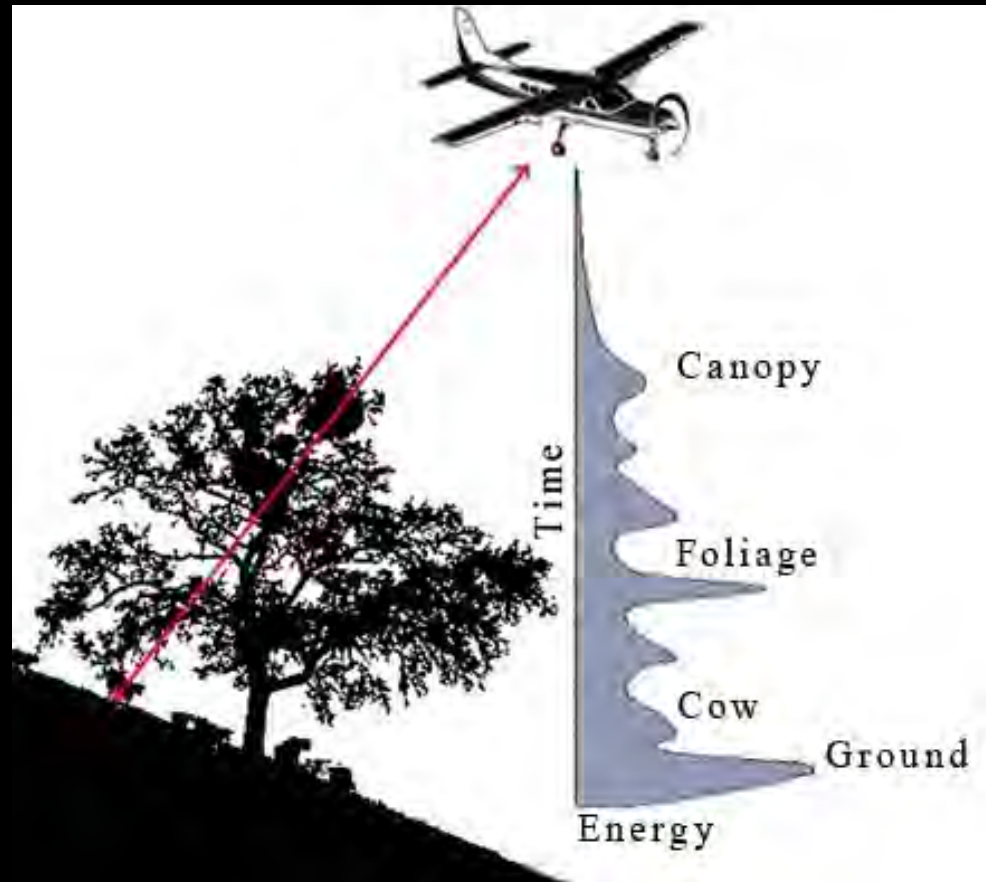
LiDAR Point Cloud



Multiple Returns

For each pulse, many returns

- Typically 1-4 returns per pulse
- Provides vertical profile
- Last returns used to determine the ground surface



LAS Attributes

POINT DATA RECORD FORMAT 1:

| Item | Format | Size | Required |
|--|----------------|---------|----------|
| X | long | 4 bytes | * |
| Y | long | 4 bytes | * |
| Z | long | 4 bytes | * |
| Intensity | unsigned short | 2 bytes | |
| Return Number | 3 bits | 3 bits | * |
| Number of Returns (given pulse) | 3 bits | 3 bits | * |
| Scan Direction Flag | 1 bit | 1 bit | * |
| Edge of Flight Line | 1 bit | 1 bit | * |
| (1.1) Classification | unsigned char | 1 byte | * |
| Scan Angle Rank (-90 to +90) – Left side | unsigned char | 1 byte | * |
| (1.1) User Data | unsigned char | 1 byte | |
| (1.1) Point Source ID | unsigned short | 2 bytes | * |
| GPS Time | double | 8 bytes | * |

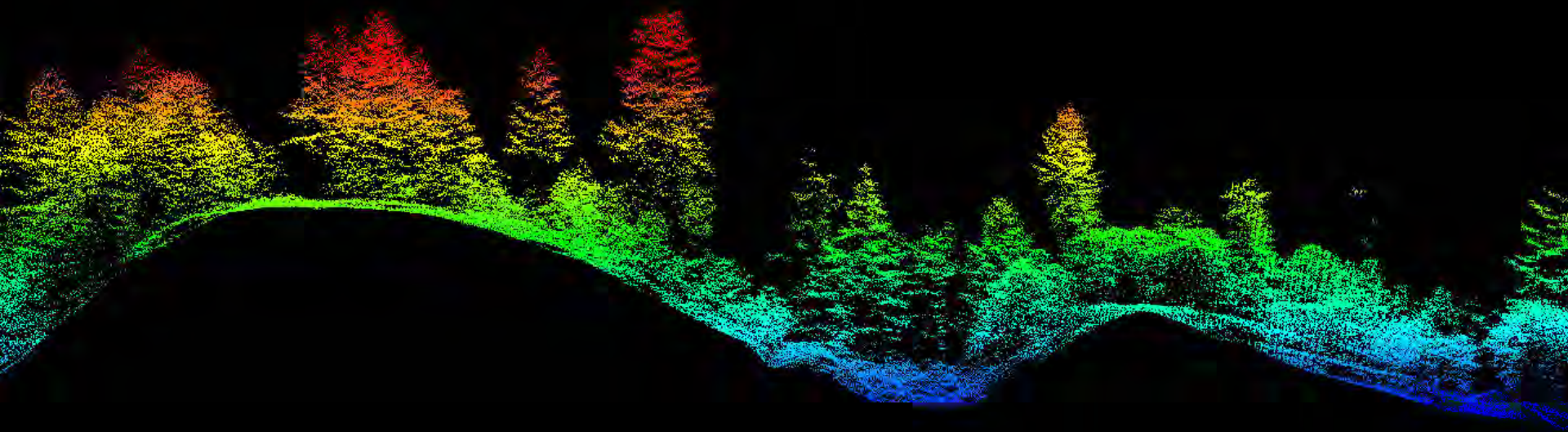
LAS Classification

ASPRS Standard LIDAR Point Classes

| <i>Classification Value (bits 0:4)</i> | <i>Meaning</i> |
|---|--------------------------------------|
| 0 | Created, never classified |
| 1 | Unclassified ¹ |
| 2 | Ground |
| 3 | Low Vegetation |
| 4 | Medium Vegetation |
| 5 | High Vegetation |
| 6 | Building |
| 7 | Low Point (noise) |
| 8 | Model Key-point (mass point) |
| 9 | Water |
| 10 | <i>Reserved for ASPRS Definition</i> |
| 11 | <i>Reserved for ASPRS Definition</i> |
| 12 | Overlap Points ² |
| 13-31 | <i>Reserved for ASPRS Definition</i> |

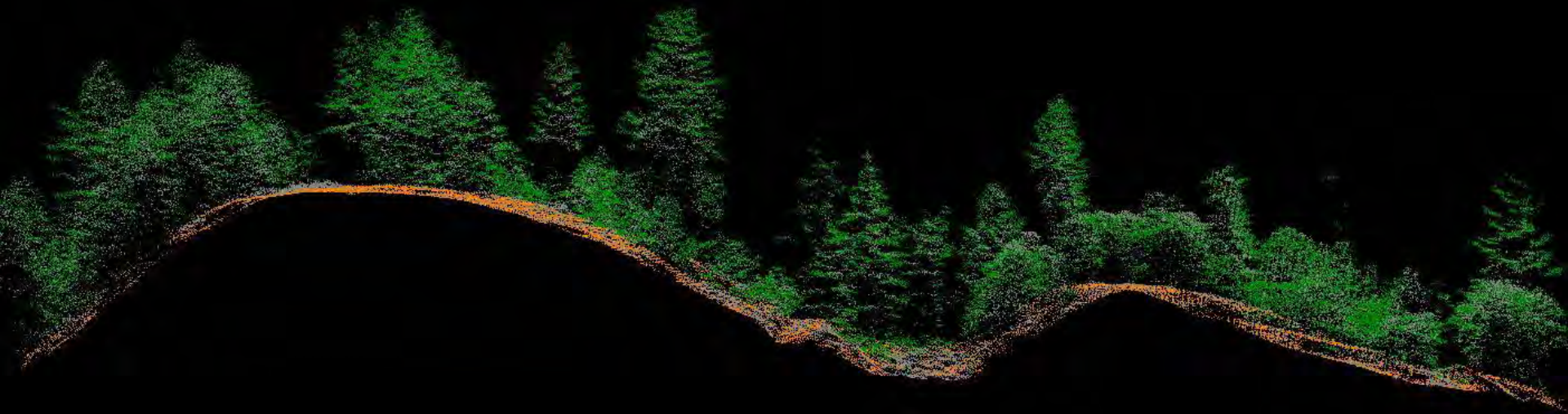
Point Cloud Profile

All Returns

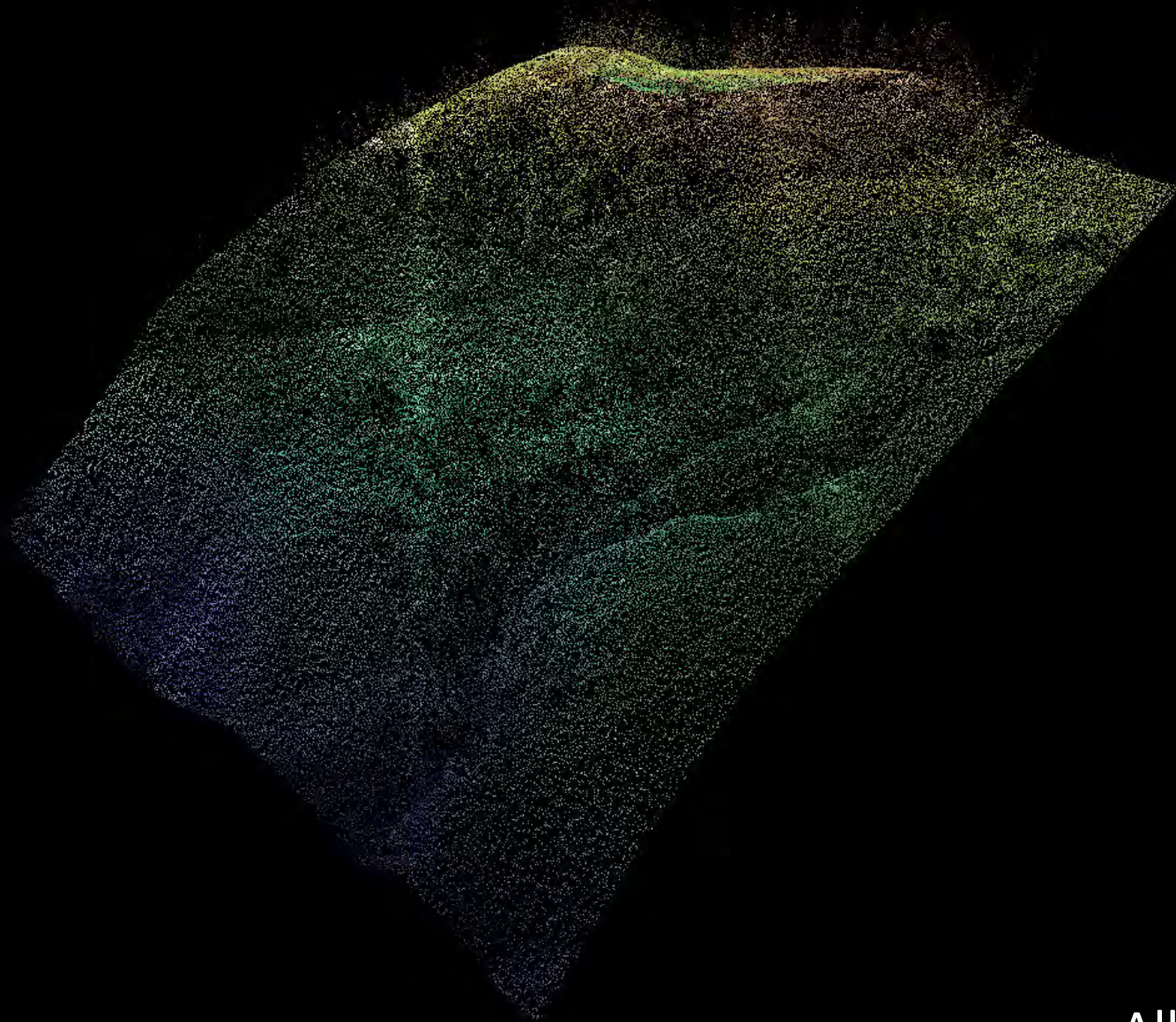


Point Cloud Profile

Classified



Point Cloud Perspective



All Returns

Point Cloud Perspective

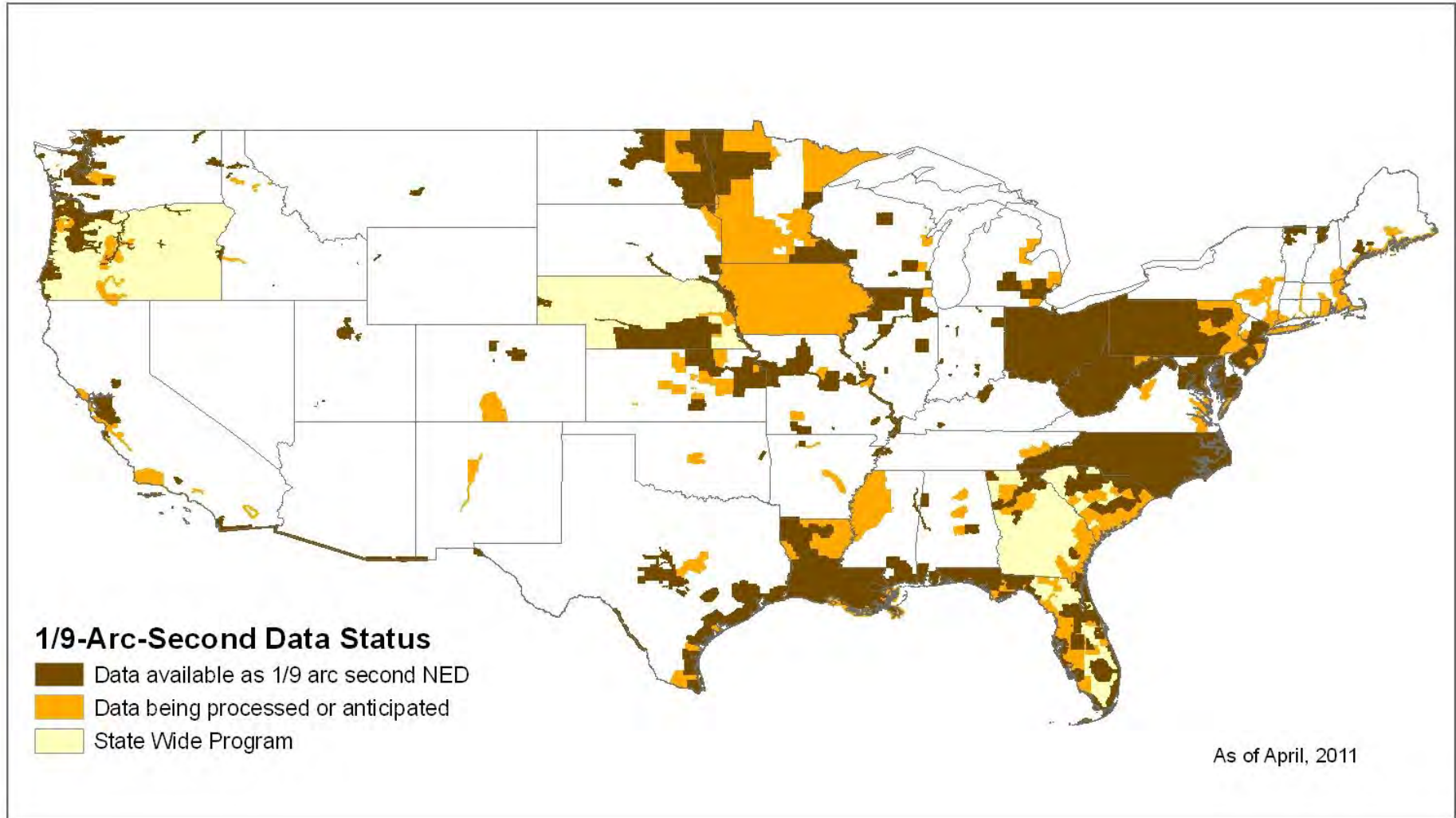


Ground Interpolation

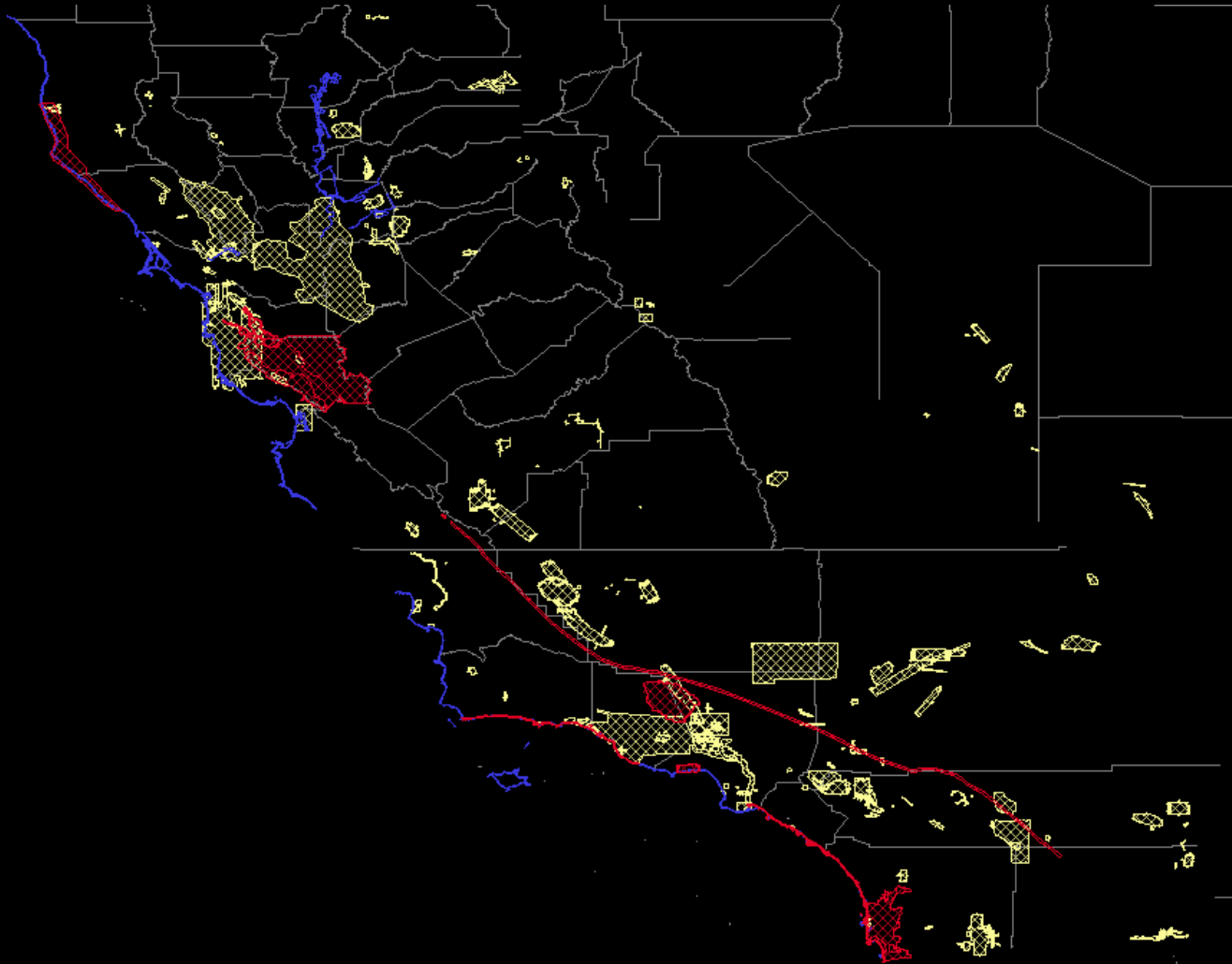
Data Sources and Products

| Source | Products |
|-------------------------|--------------------------|
| • Contract, Resale Data | LAS classified, DEM, ... |
| • USGS Click | LAS unclassified |
| • Seamless NED, TNM | 3m DEM |

The National Map



USGS Click



LiDAR Basemaps

Oregon Department of Geology

1 : 8000 map scale

Bare-Earth, Contours, Hydrography

Surface Height Hillshade
with 4-tone tint

Can order print, .pdf, or data DVD

<http://www.oregongeology.com/sub/pub&data/lidarpubs.htm>



DOGAMI Lidar Imagery (LIS) Series Publications



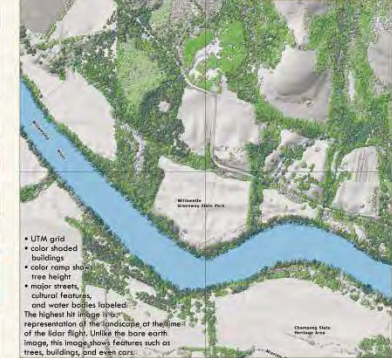
What does each LIS publication contain?

DOGAMI Lidar Imagery Series publications are PDF files that contain bare earth digital elevation model (DEM) images and highest hit DEM images of a selected area, generally the four quarter quadrants (NW, NE, SW, and SE) of a 7.5' USGS topographic quadrangle.

LIDAR BARE EARTH DATA



LIDAR HIGHEST HIT DATA



SE quarter of Newberg
7.5' quadrangle
Ohio Code 45122C84
• scale 1:8,000
• 360 dpi



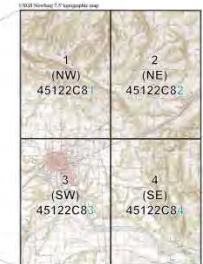
4 quarter quadrangle map sheets in each 7.5' quadrangle publication. Each quarter quadrangle sheet contains a bare earth and a highest hit image.



Understanding the Ohio Code Grid System

The Ohio code grid system splits a 1" x 1" grid block into sixty-four 7.5' quadrangles. The Ohio code values are derived from the latitude and longitude of the SE corner of the 1" x 1" block and an assigned grid number. The grid system starts in the lower right hand corner of each 1" grid block and uses the latitude and longitude as a prefix to a six digit section.

For example, the gray 1" x 1" block shown below is defined by the 46° latitude line and the 122° longitude line, which are concatenated to form the "46122" block. The 1" x 1" block is broken into eight rows of quadrangles along latitude by eight columns of quadrangles along longitude to define the sixty-four 7.5' quadrangles. A two-character grid number that defines the row (A-H, bottom to top) and column (1-8, right to left) is assigned to each 7.5' section (see illustration to the right).



Example: U.S. Geological Survey Newberg 7.5' topographic quadrangle, Ohio code 45122C84

First 2 characters: latitude of SE corner of quadrangle, i.e., 45
Next 3 characters: longitude of SE corner of quadrangle, i.e., 122
Next character: A-H lettering scheme (the rows of the 1" block labeled bottom to top), i.e., C
Next character: 1-8 numbering scheme (the columns of the 1" block labeled right to left), i.e., 4

quadrangle
quadrant (1-4,
numbered west to
east, north to south)

For more information about lidar and the Oregon Lidar Consortium, visit www.OregonGeology.org

CCJDC 2010















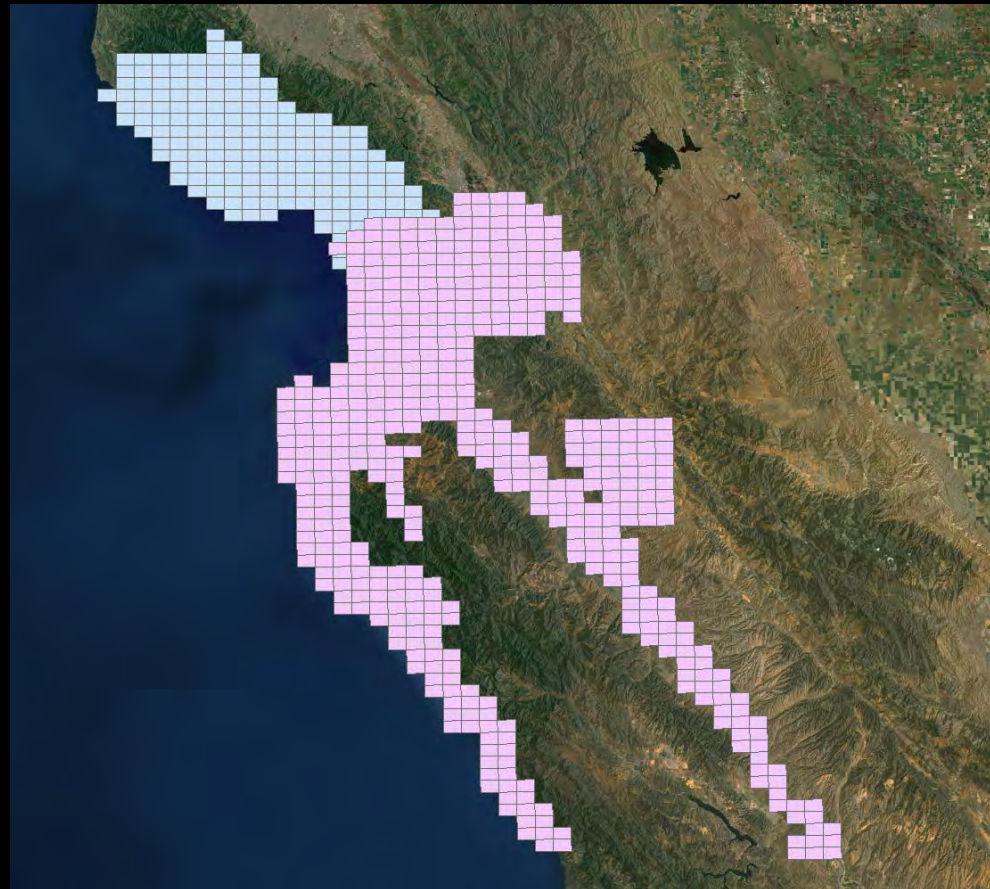
<http://www.ccjdc.org/projects/lidar.htm>

LiDAR .LAS data

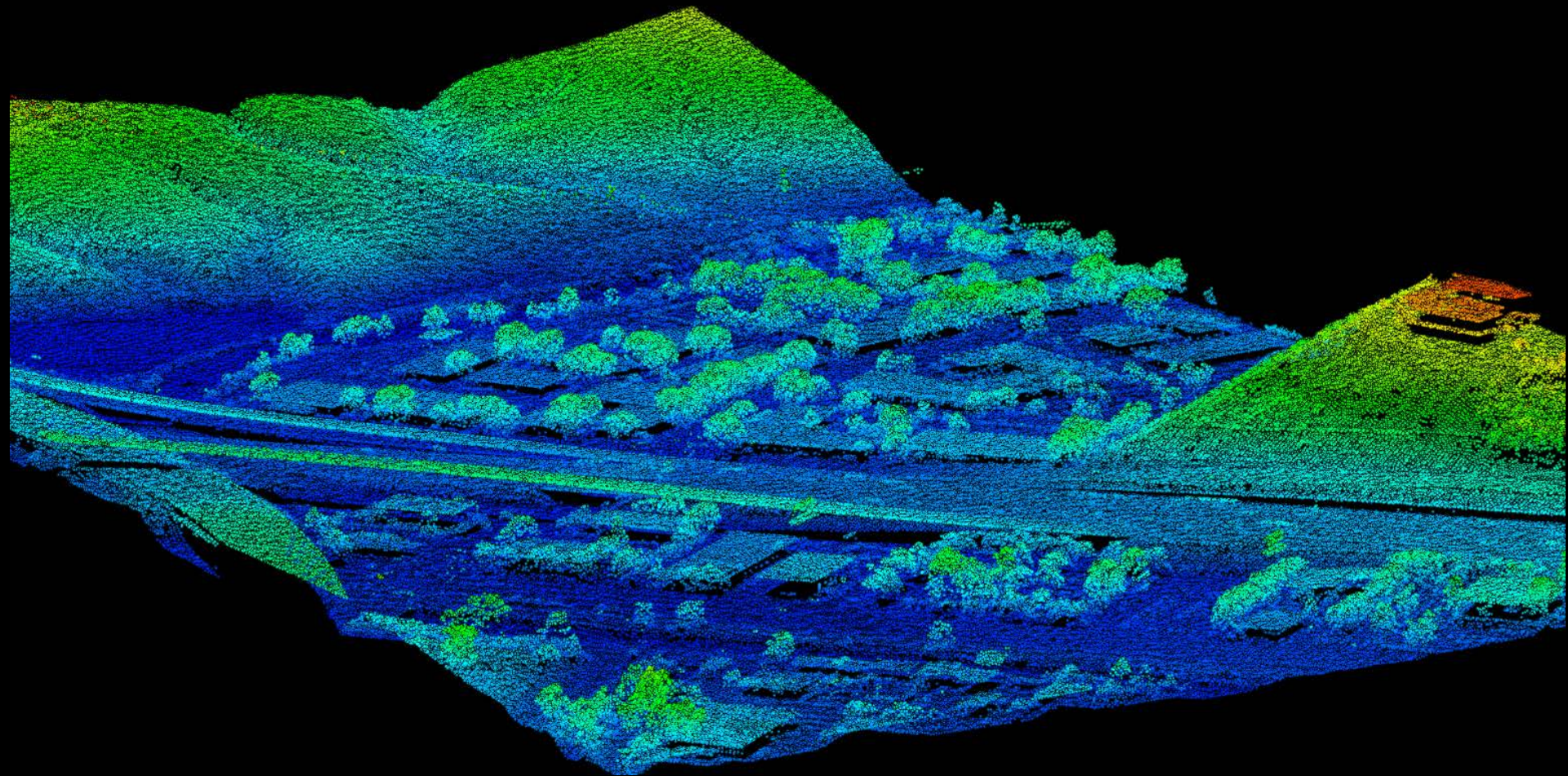
- 683 Tiles
- 25 Million points ea.
- ~500 Mb ea.

3.4 Mi² ea

| Name | Date modified | Type | Size |
|--|-------------------|----------|------------|
|  4BG-15.las | 3/31/2011 8:09 AM | LAS File | 441,915 KB |
|  4BH-14.las | 3/31/2011 8:09 AM | LAS File | 38,425 KB |
|  4BH-15.las | 3/31/2011 8:09 AM | LAS File | 549,728 KB |
|  4BH-16.las | 3/31/2011 8:09 AM | LAS File | 603,909 KB |
|  4BI-14.las | 4/1/2011 7:29 AM | LAS File | 126,098 KB |
|  4BI-15.las | 3/31/2011 8:09 AM | LAS File | 590,930 KB |
|  4BI-16.las | 3/31/2011 8:09 AM | LAS File | 616,355 KB |
|  4BI-17.las | 3/31/2011 8:09 AM | LAS File | 603,956 KB |
|  4BI-18.las | 3/31/2011 8:09 AM | LAS File | 612,503 KB |
|  4BI-19.las | 3/31/2011 8:09 AM | LAS File | 613,137 KB |
|  4BI-20.las | 3/31/2011 8:09 AM | LAS File | 591,898 KB |
|  4BI-21.las | 3/31/2011 8:09 AM | LAS File | 603,141 KB |



Layers from LAS data?



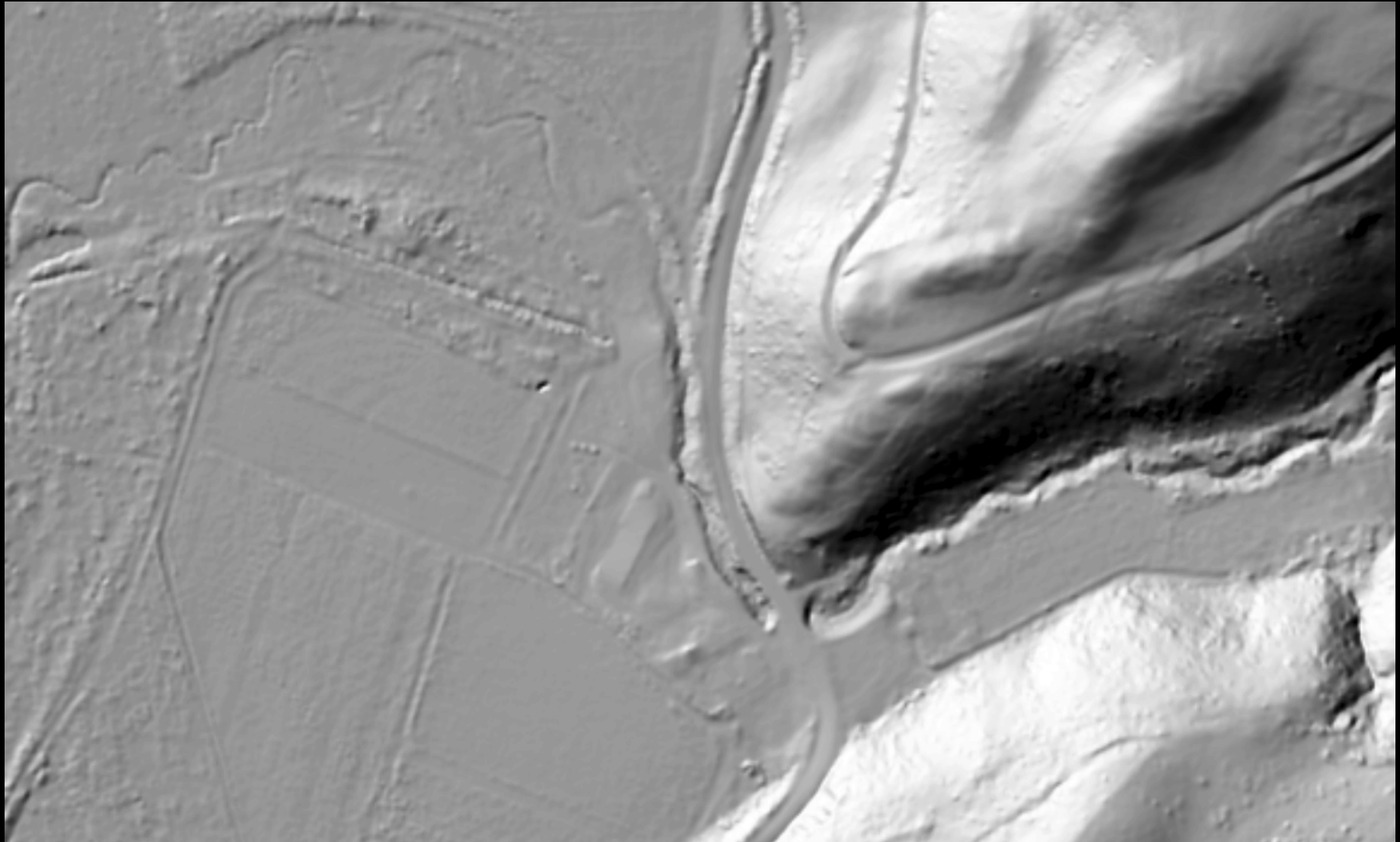
Grid Layers from LAS

- Bare Earth DEM
- Canopy Height Model
- Intensity Image
- % Canopy Cover, Bulk Density,
Height to Crown Base, ...
- Ground Point Density

Bare Earth DEM

data must already be filtered

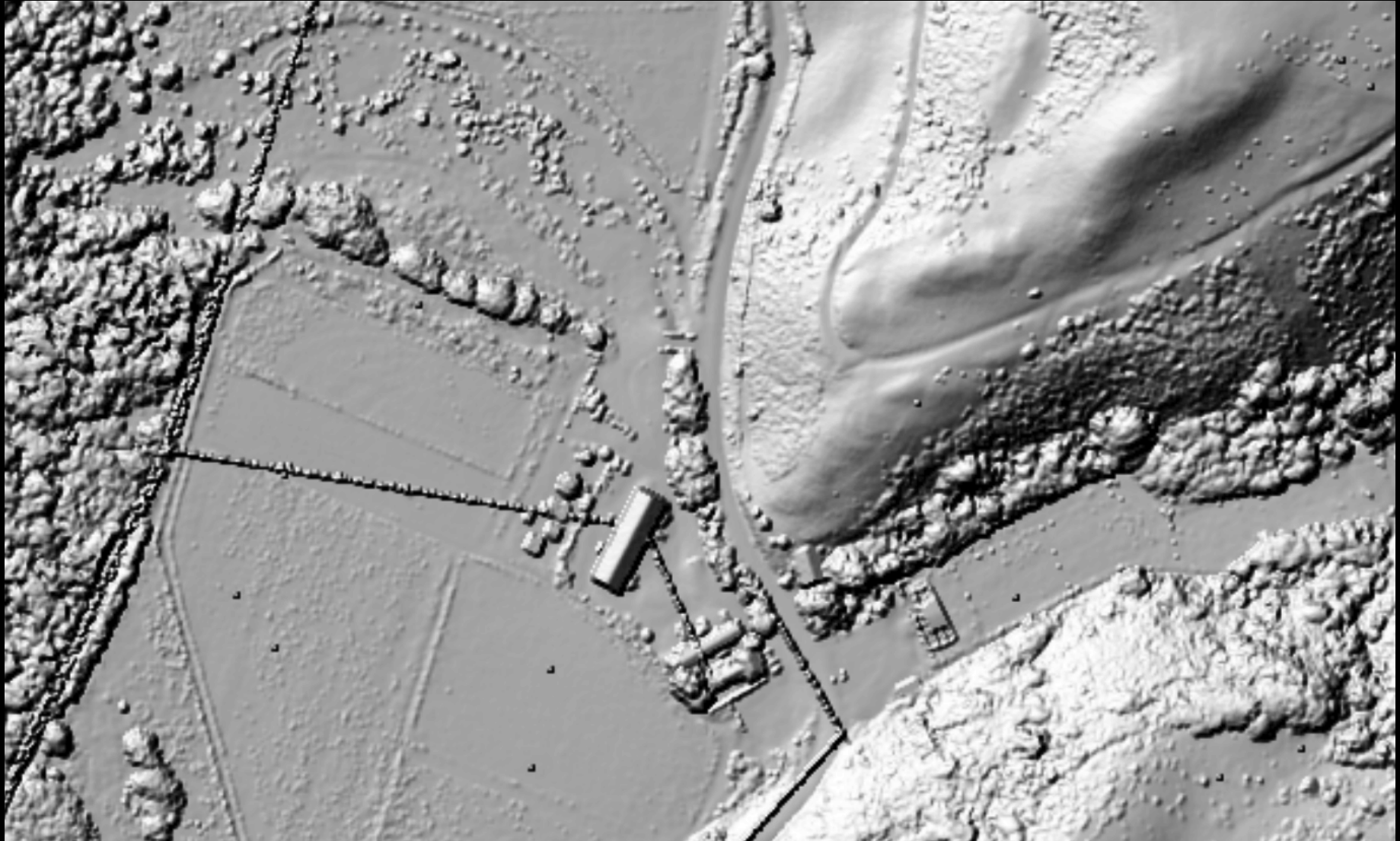
ArcGIS



Digital Surface Model (DSM)

Highest hit elevations

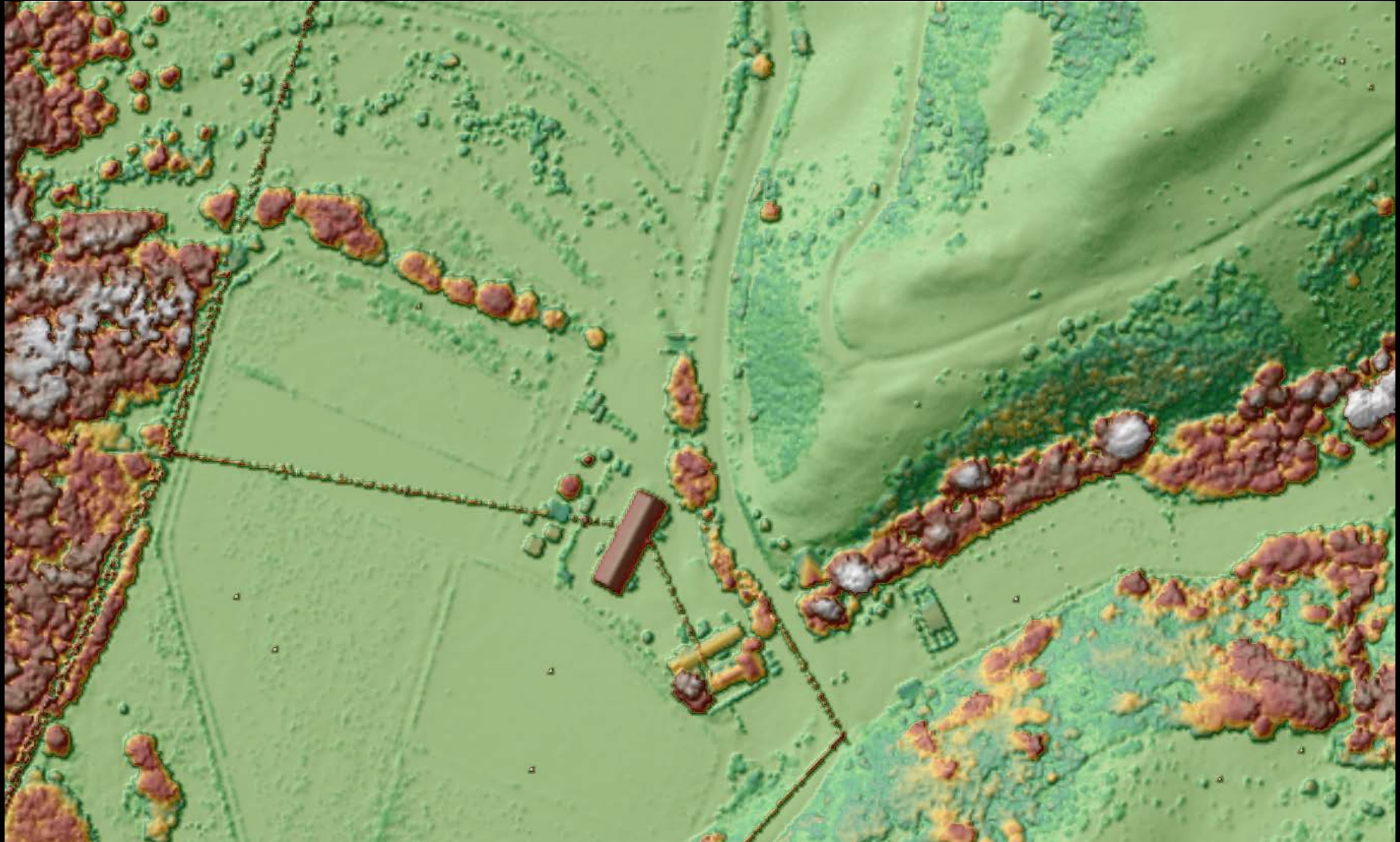
USFS Fusion



nDigital Surface Model (nDSM)

DSM – DEM = height above ground

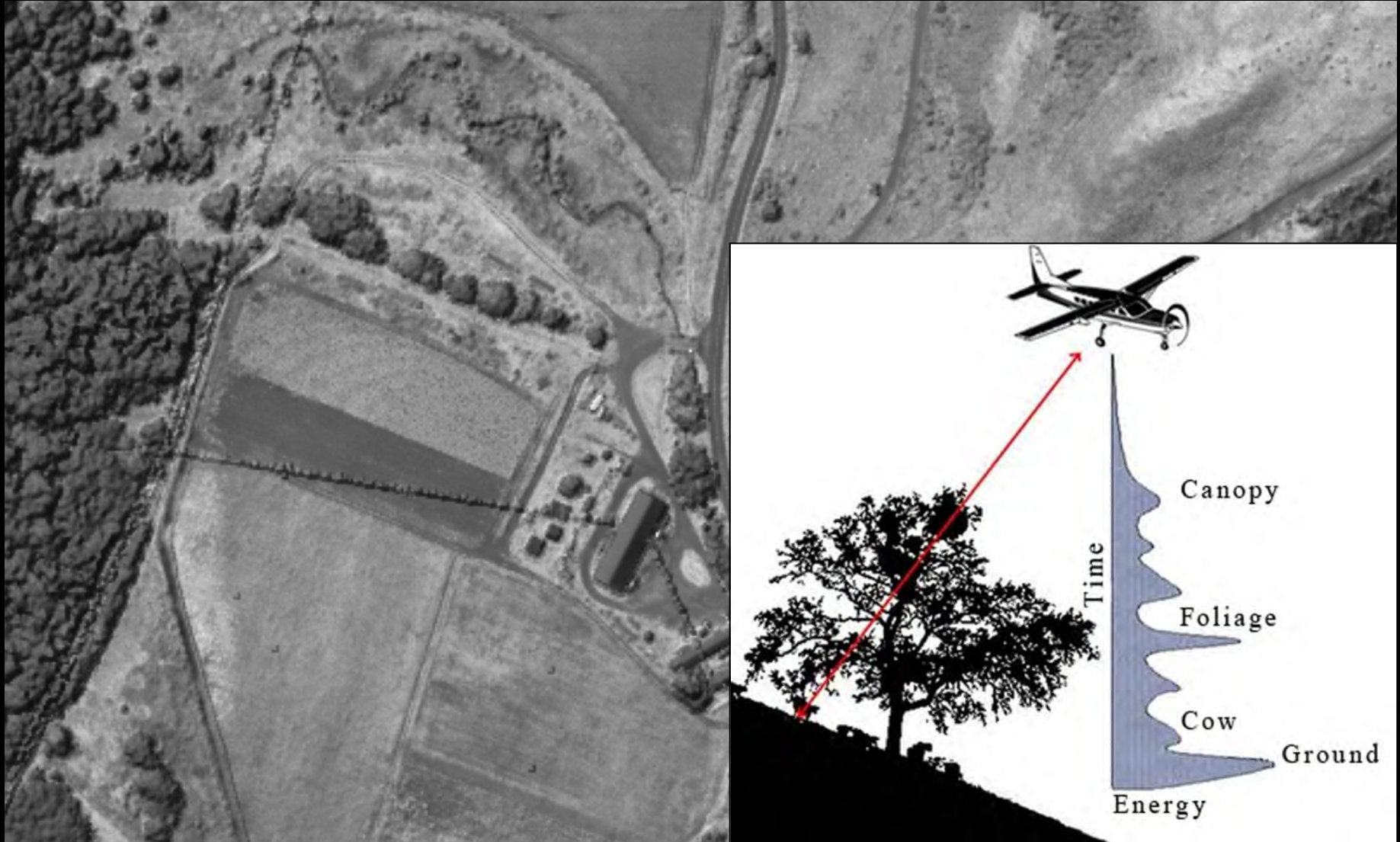
ArcGIS



Intensity Image

LiDAR reflectance

ArcGIS: Point to Raster*



Hillshade and Imagery

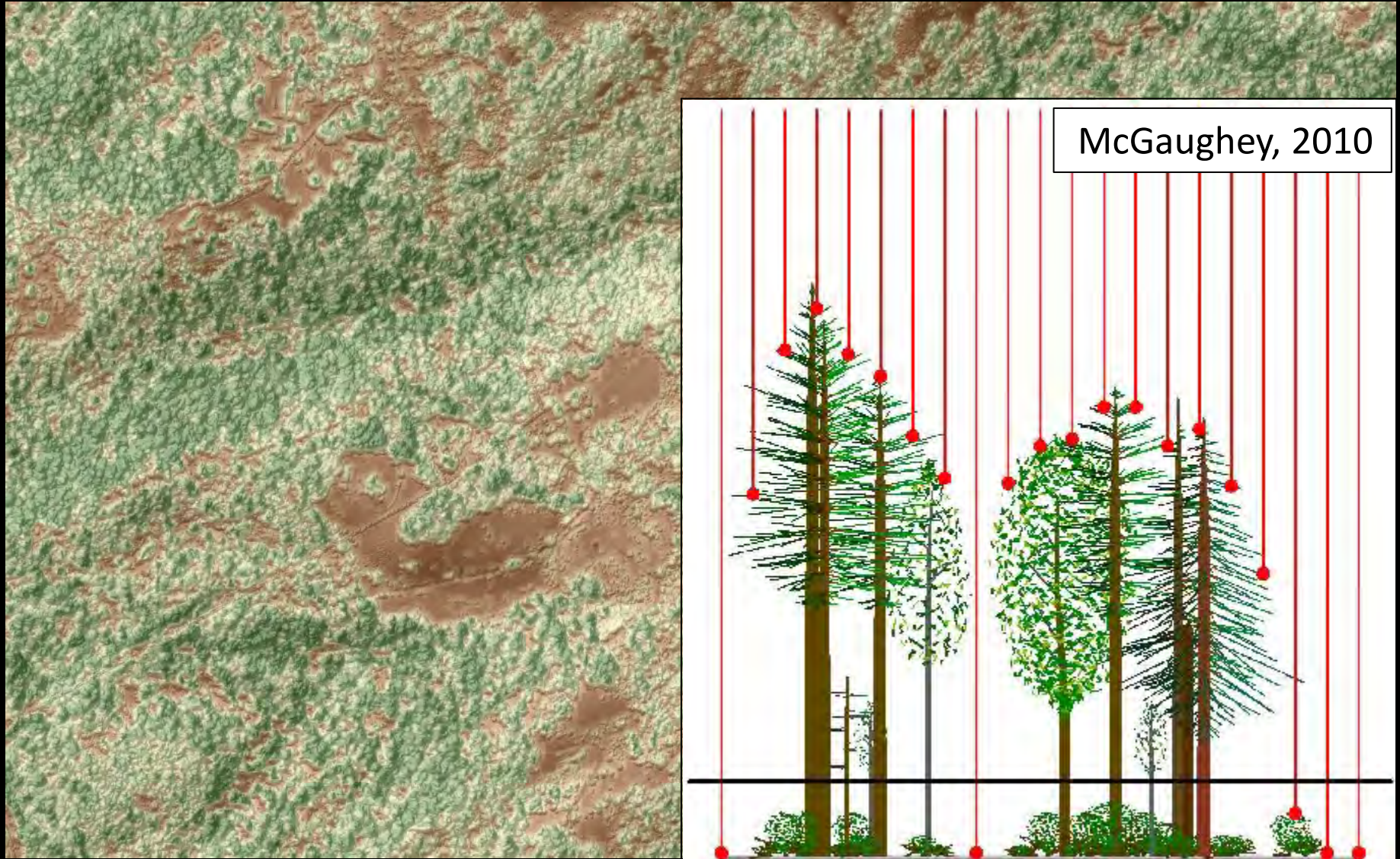
ArcGIS



Percent Canopy Cover

(# Canopy returns / Total # Returns)

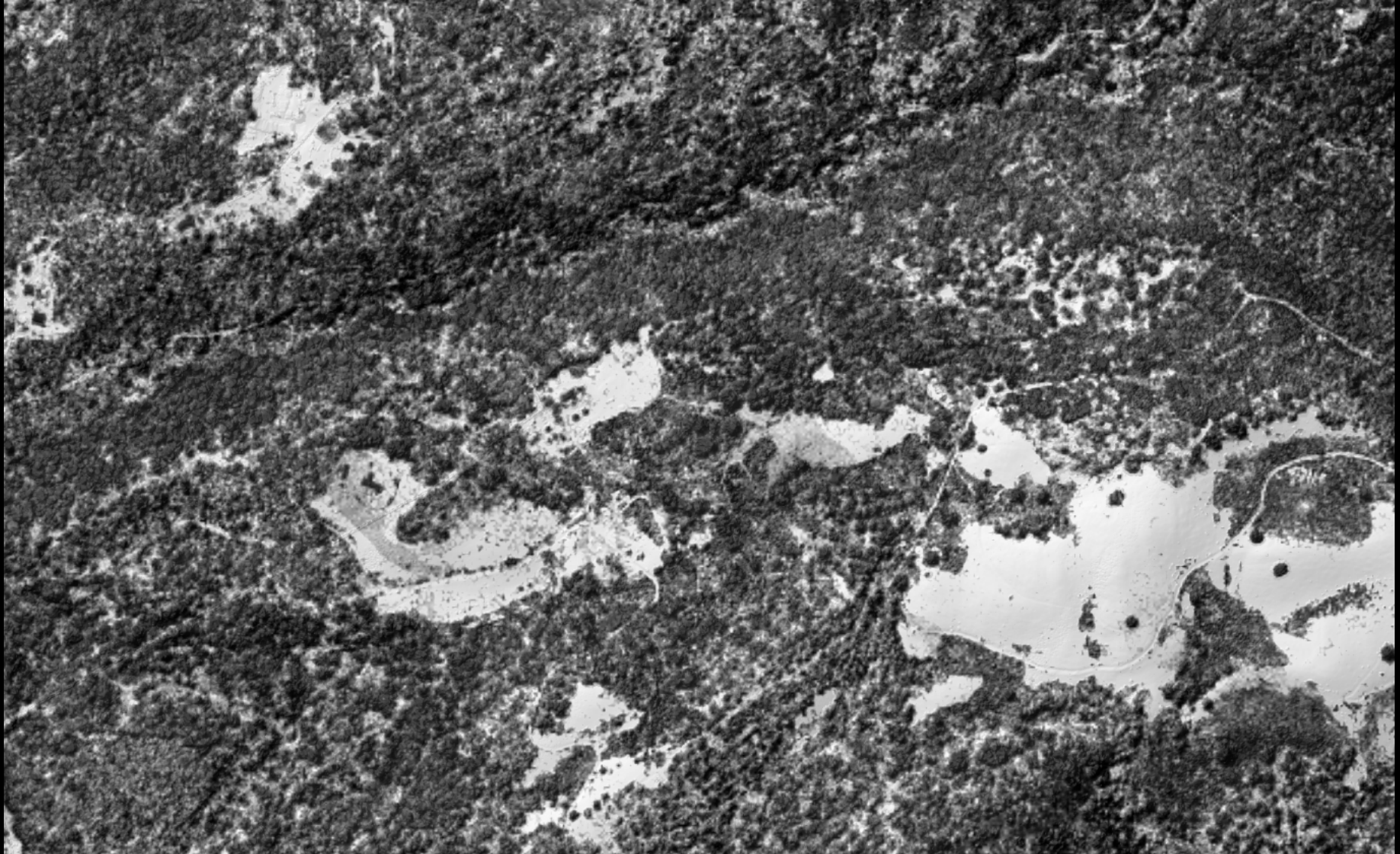
USFS Fusion



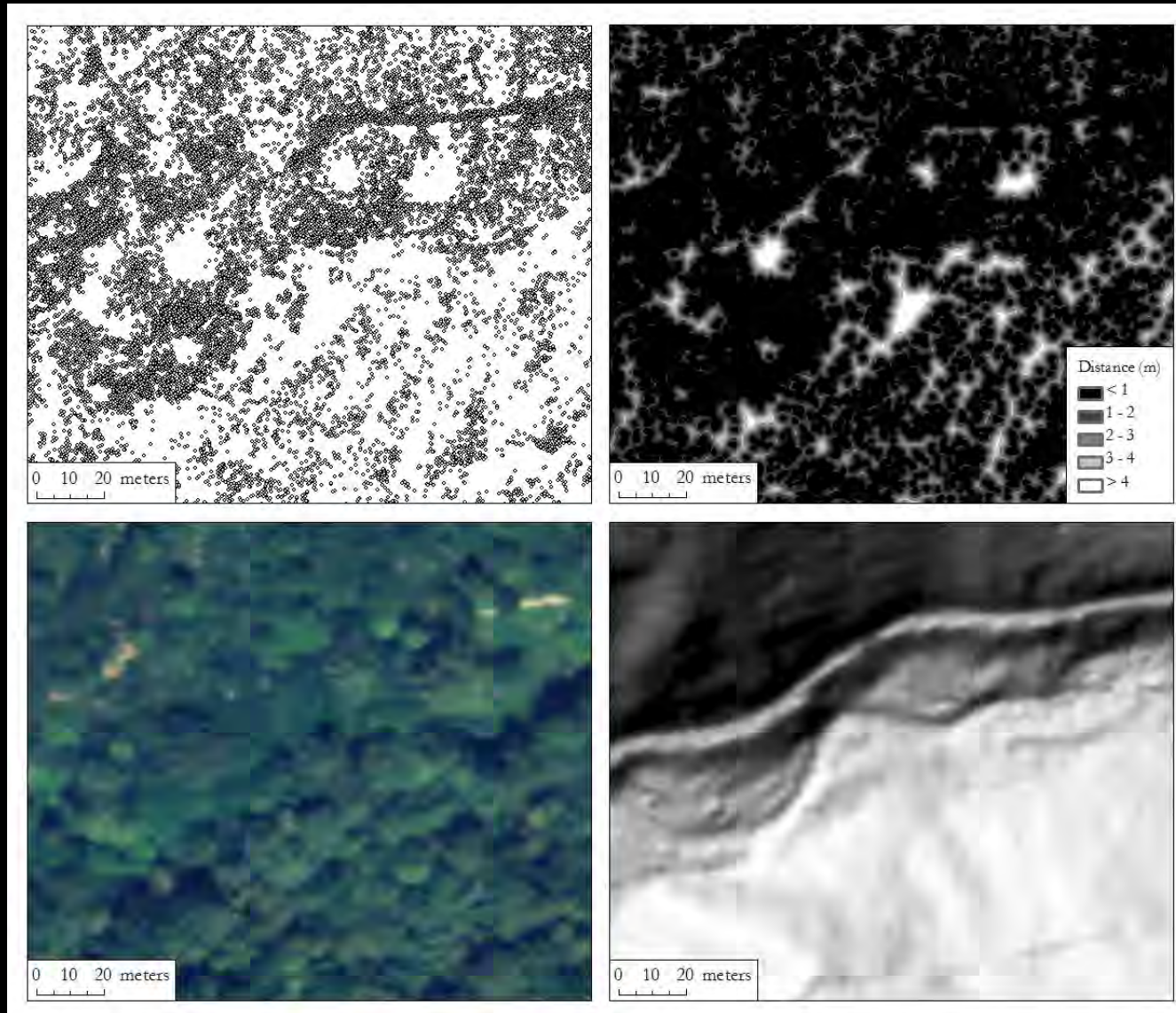
Ground Point Density

Ground Returns per m²

Point to Raster

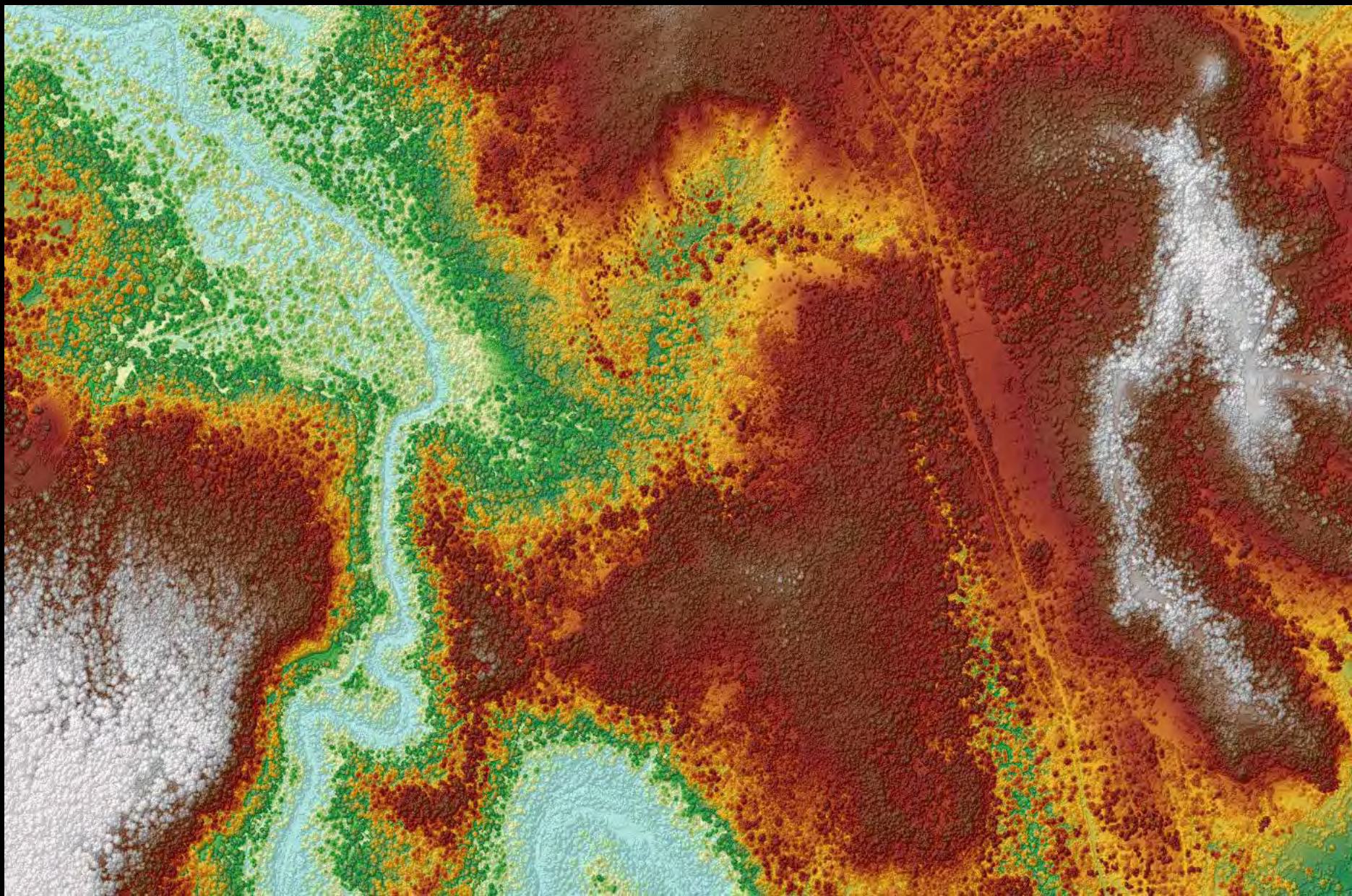


Irregular Point Spacing



CCJDC Example Data

- Tile 4BP-9.las
 - Bare Earth Hillshade
 - DSM
 - nDSM
 - Canopy Cover
 - Intensity
 - Original Bare-earth Filtering v.s. MCC re-filter





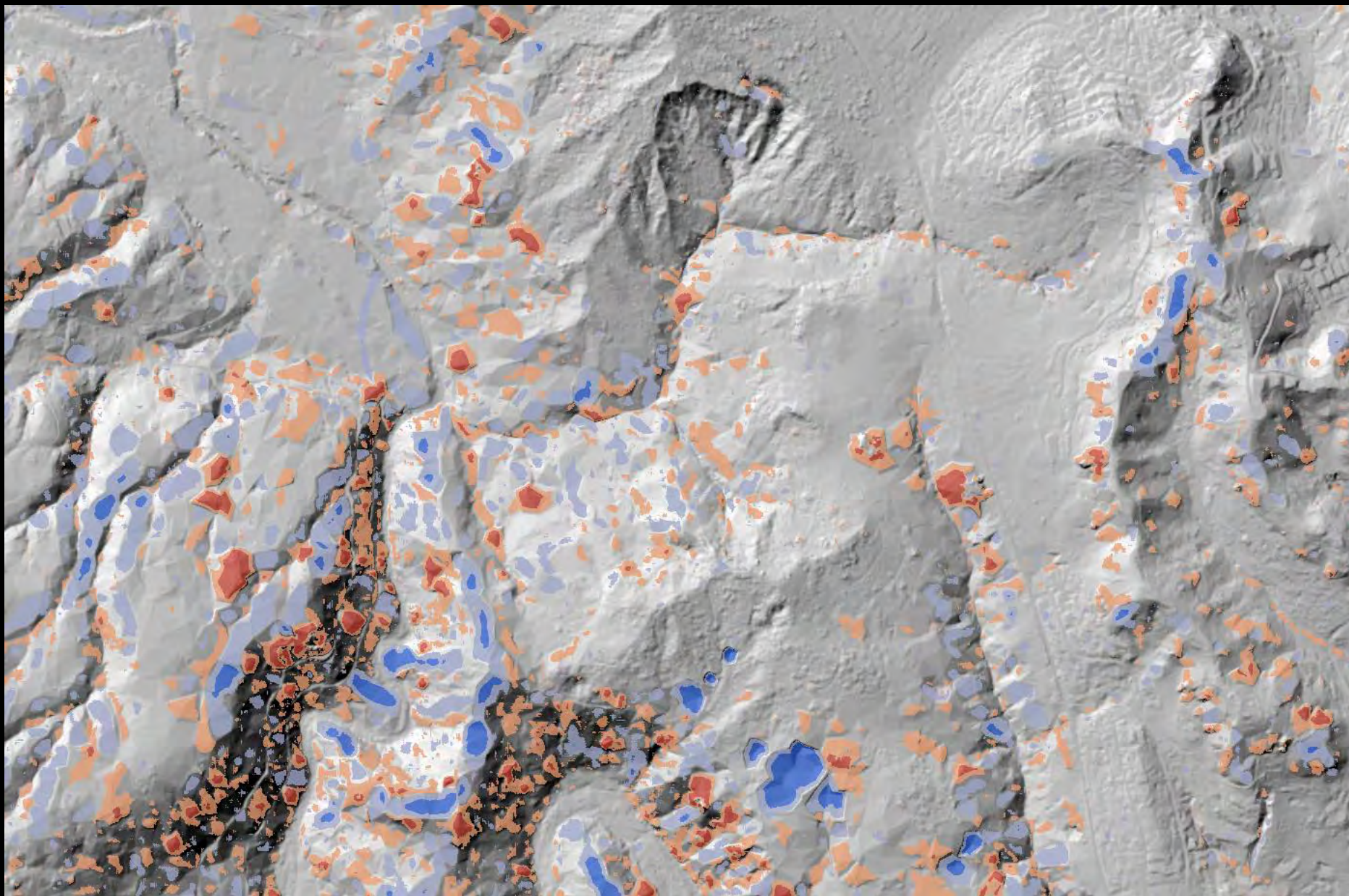












Elevation Difference from Original DEM- Refiltered DEM: +100 to – 100 ft.



Original Ground Point Density 0-2 pts./m²

Visualization and Processing Tools

LP360

Point Cloud Viewer

LAS Tools

Clip, Merge, Convert...

MCC-LIDAR

Bare Earth Filtering

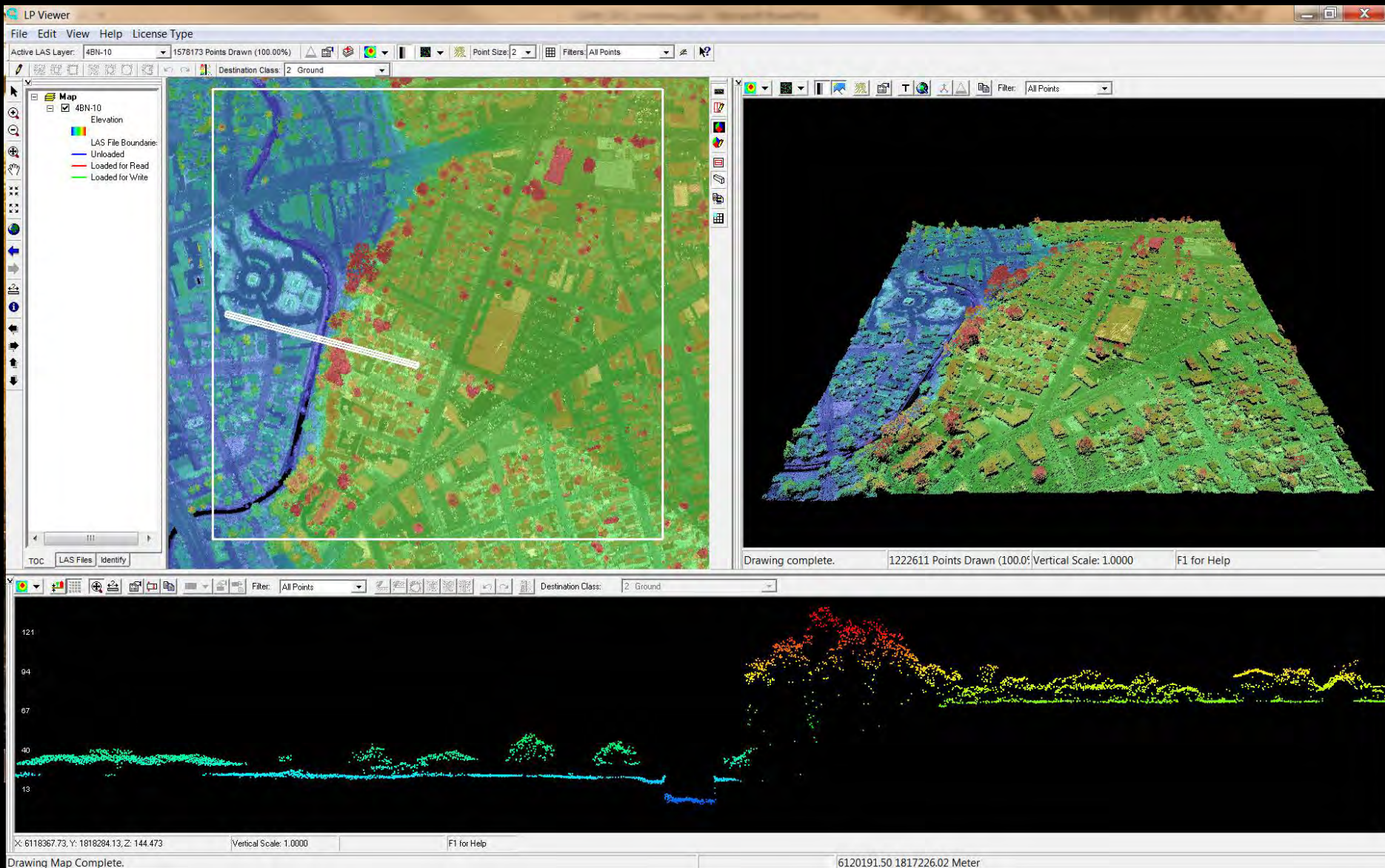
USFS Fusion

Canopy Surface, and more

ArcGIS

Build TIN, Terrain, DEM

Qcoherent LP360



LAS Tools

LasClip: extract points within polygon

- `LasClip -i in.las -o out.las -poly mask.shp`

Keep Only Ground Returns

- `las2las -i in.las -o out.las -keep_class 2`

Merge many tiles into one

- `LasMerge -i list.txt -o merged.las`

LAS Tools

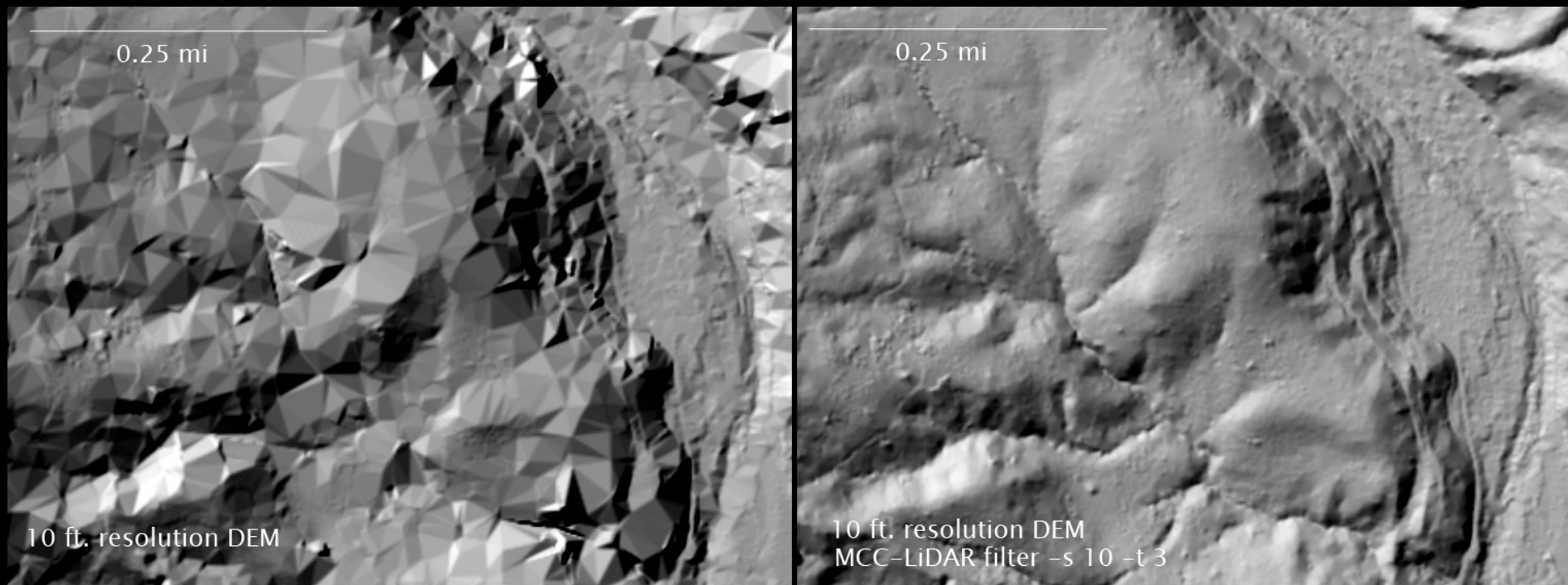
| | |
|--------------|--|
| laszip.exe | compresses the LAS files in a completely lossless manner |
| lasinfo.exe | prints out a quick overview of the contents of a LAS file |
| txt2las.exe | converts LIDAR data from ASCII text to binary LAS format |
| las2txt.exe | turns LAS into human-readable and easy-to-parse ASCII text |
| lasmerge.exe | merges several LAS files into one |
| lasgrid.exe | rasters very large LAS files into elevation or intensity grids |
| lastile.exe | tiles huge amounts of LAS points into square tiles |

LAS Tools Continued

| | |
|-------------|---|
| lasclip.exe | clips LAS points against building footprints / swath boundaries ... |
| las2las.exe | extracts last returns, clips, subsamples, translates, etc ... |
| lasboundary | extracts a boundary polygon that encloses the points |
| las2tin.exe | triangulates the points of a LAS file into a TIN |
| las2dem.exe | rasters a temporary TIN with hillshade/elevation/intensity |
| las2iso.exe | extracts, optionally simplified, elevation contours |
| las2shp.exe | turns binary LAS into ESRI's Shapefile format |
| shp2las.exe | turns an ESRI's Shapefile into binary LAS |

MCC-LiDAR

Open Source Bare Earth Filtering



```
mcc-lidar -s 8 -t 3 sc.las sc_filtered.las
```

USFS Fusion

CanopyMaxima

CanopyModel

Catalog

ClipData

ClipDTM

CloudMetrics

Cover

DensityMetrics

FilterData

FirstLastReturn

GridMetrics

GridSurfaceCreate

GroundFilter

IntensityImage

MergeData

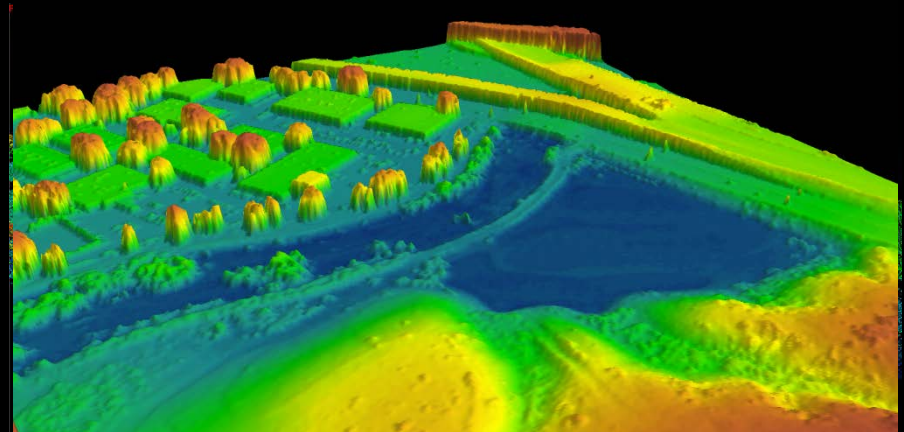
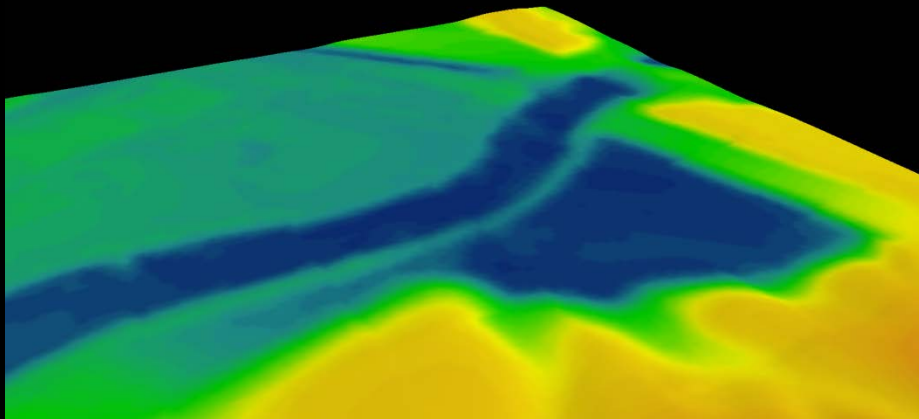
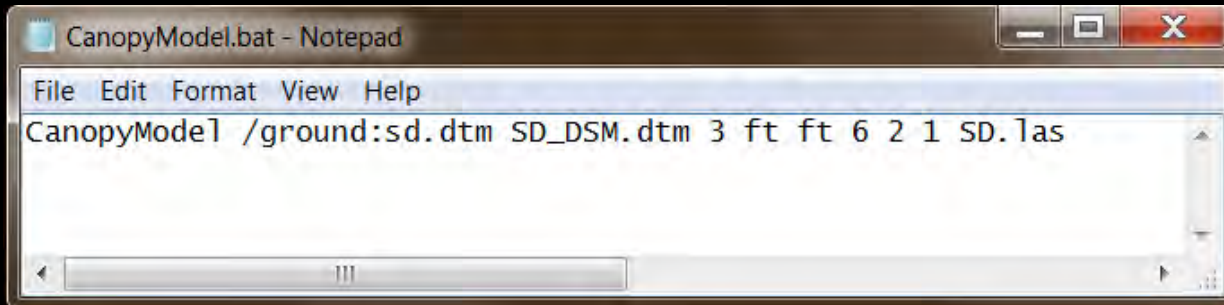
MergeDTM

PolyClipData

USFS Fusion: Canopy Surface Model

Syntax

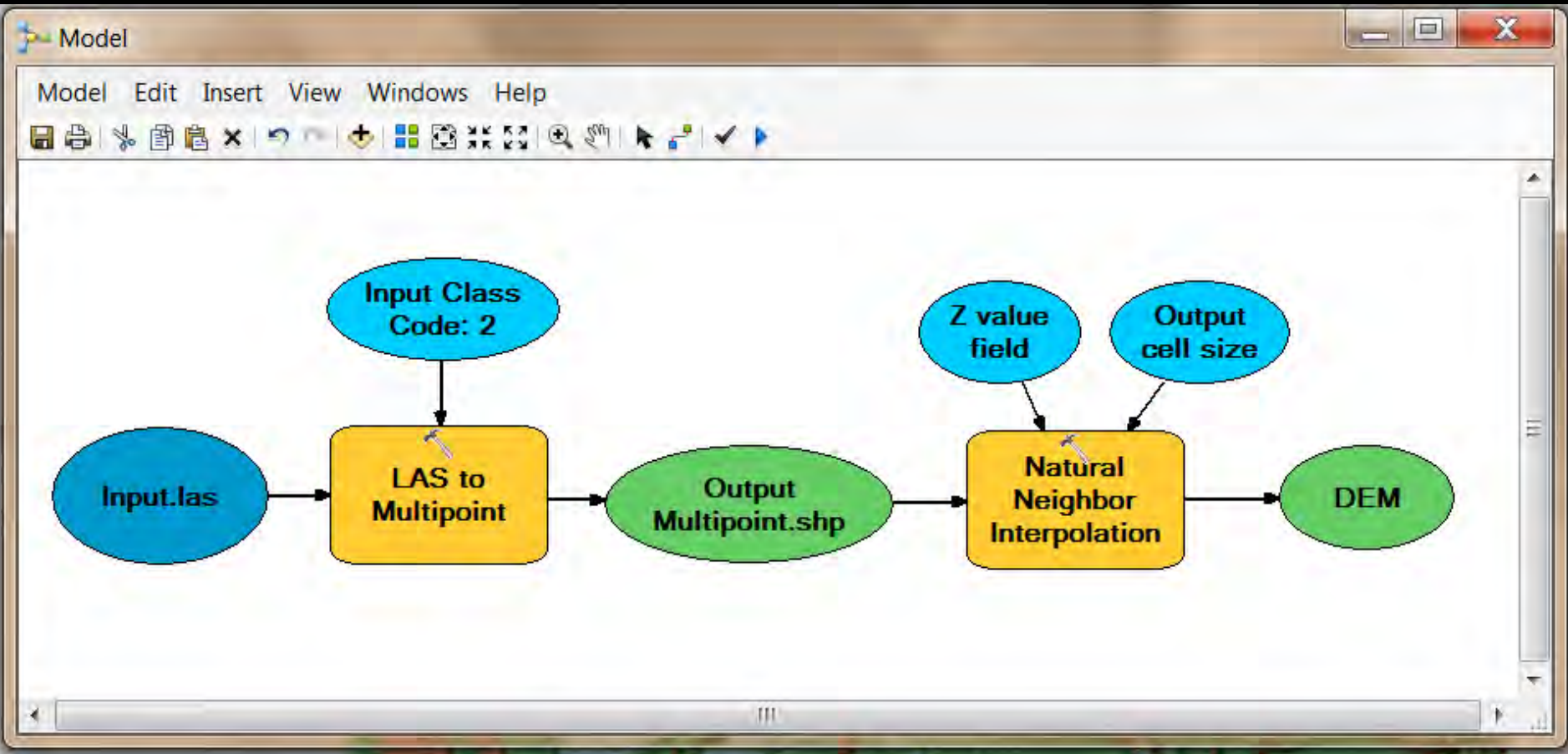
*CanopyModel [switches] surfacefile cellsize xyunits zunits coordsys zone horizdatum
vertdatum datafile1 datafile2 ...*



LAS and ArcGIS

- If LAS data are classified:
 - LAS to Multipoint
 - Build DEM
 - Incorporate Breaklines
 - Construct Intensity Image
 - Point Density

ArcGIS: LAS to Multipoint to DEM



ArcGIS Resource Center: LiDAR Solutions in 8 parts

http://blogs.esri.com/Dev/blogs/geoprocessing/archive/2008/11/06/Lidar-Solutions-in-ArcGIS_5F00_part-1_3A00_Assessing-Lidar-Coverage-and-Sample-Density.aspx

LiDAR Software

- Several Open-Source Tools
 - Functionality for the Point Cloud
 - Stable, High performance, batch process
 - No Interactive Editing
 - No single All-purpose product
 - Data Conversion LAS → .asc → GRID
 - Some gaps in functionality

Data Considerations

- Potential value with raw LAS data
 - Also some issues: Negative Blunders, Birds...
- Processed DEMs may be suitable in the open...but
 - Inspect Hillshade
 - Evaluate Ground Point Spacing
 - Re-filter?
 - Where possible, verify with ground elevation checkpoints

GIS of the Future...today

thank you



...Questions?

Additional Links and Resources

- [Opentopography](#)
- [NCALM](#)
- [NOAA Digital Coast](#)
- [LiDAR News Blog](#)

Regional LiDAR Groups

- [Oregon DOGAMI](#)
- [Pennsylvania LiDAR](#)